



University of Idaho

College of Engineering

VIRTUAL SYNCHRONOUS GENERATOR CONTROLLER PERFORMANCE AND EVALUATION

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I Virtual Synchronous Generator Controller Structure

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Introduction

I Effect of inertia and damping of SGs on system's stability.

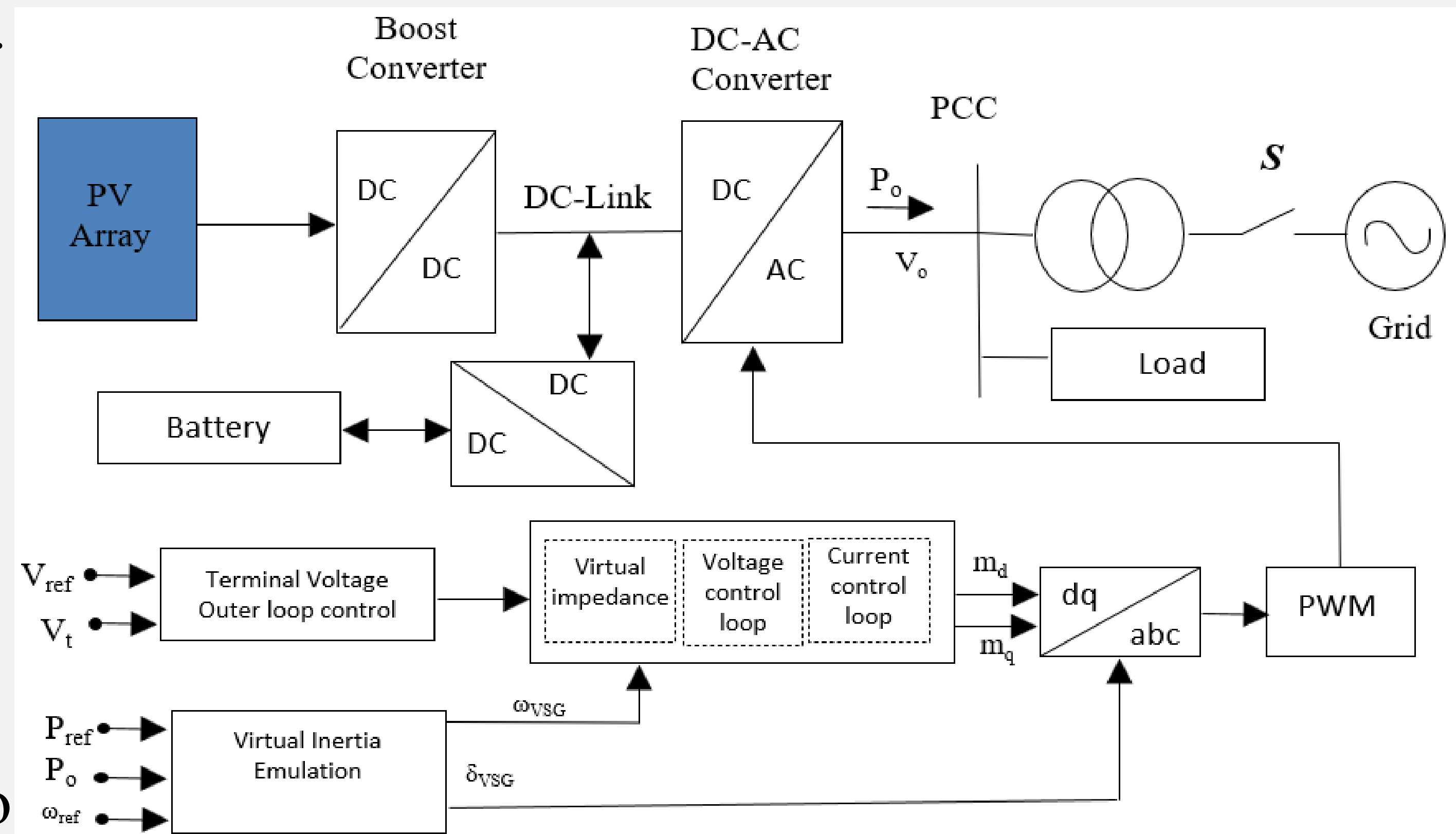
I Effect of inverter-based RERs on system inertia.

This paper would describe:

I VSG controller structure

I ESS

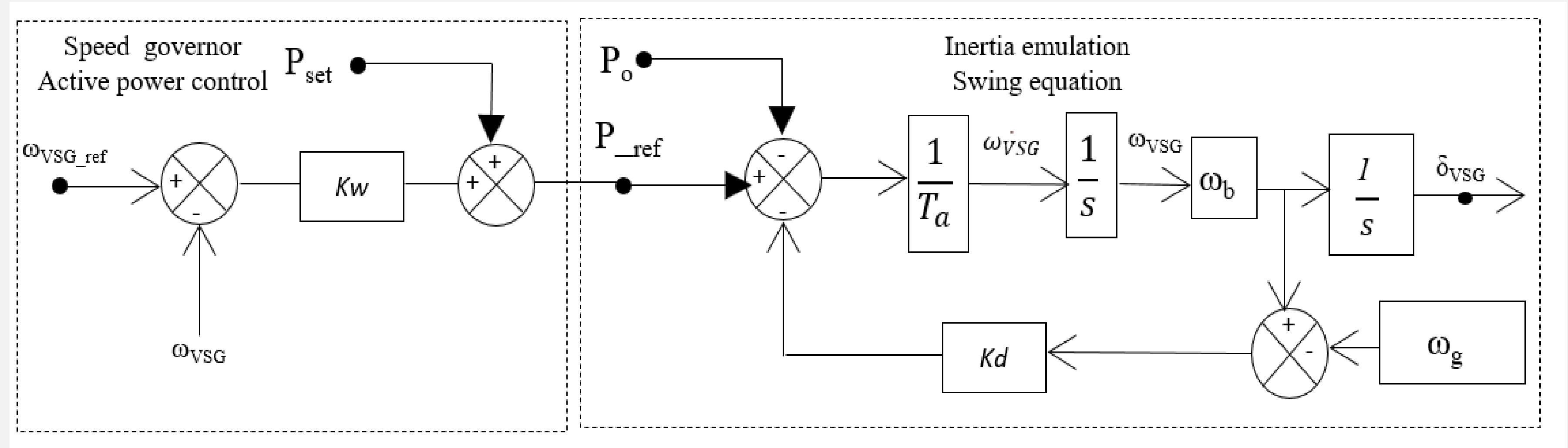
I Simulation results for different scenario



General layout of the proposed system

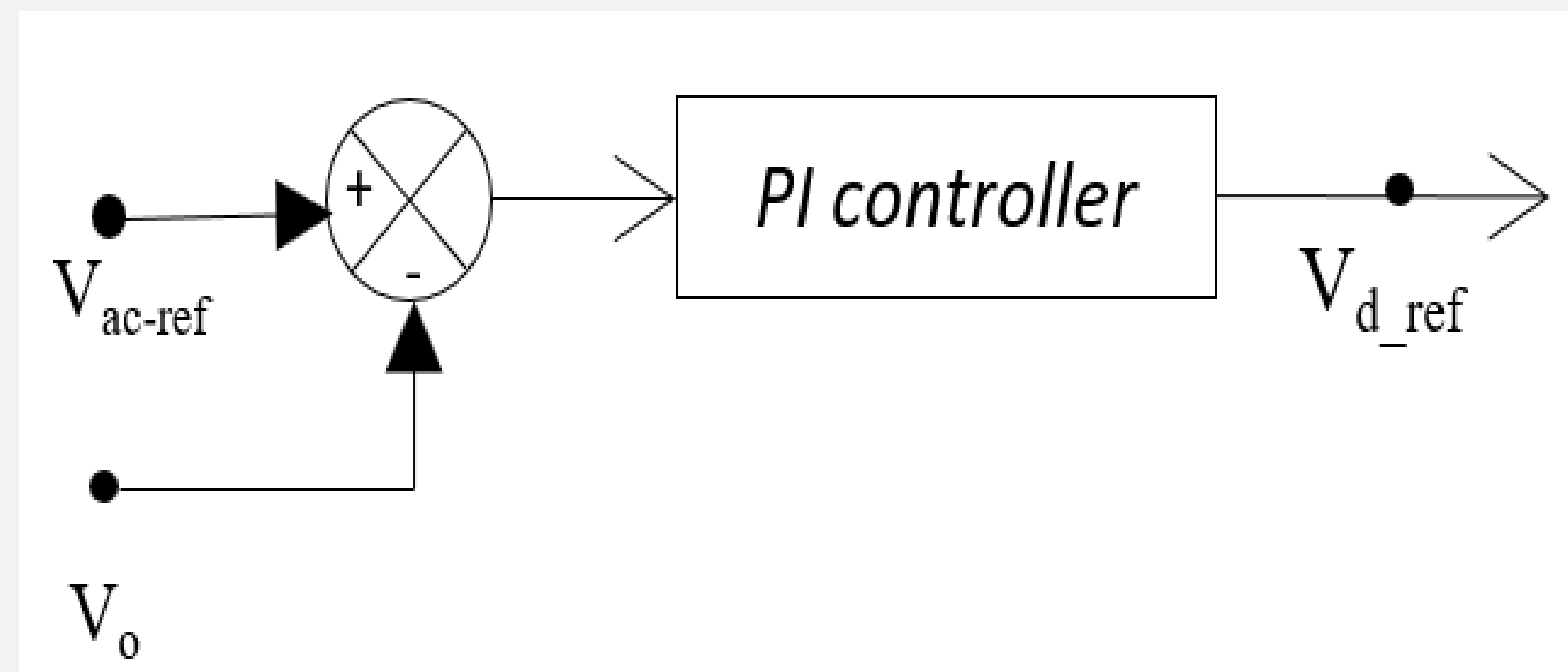
DC-AC converter controller

Outer loops:
Virtual inertia emulation



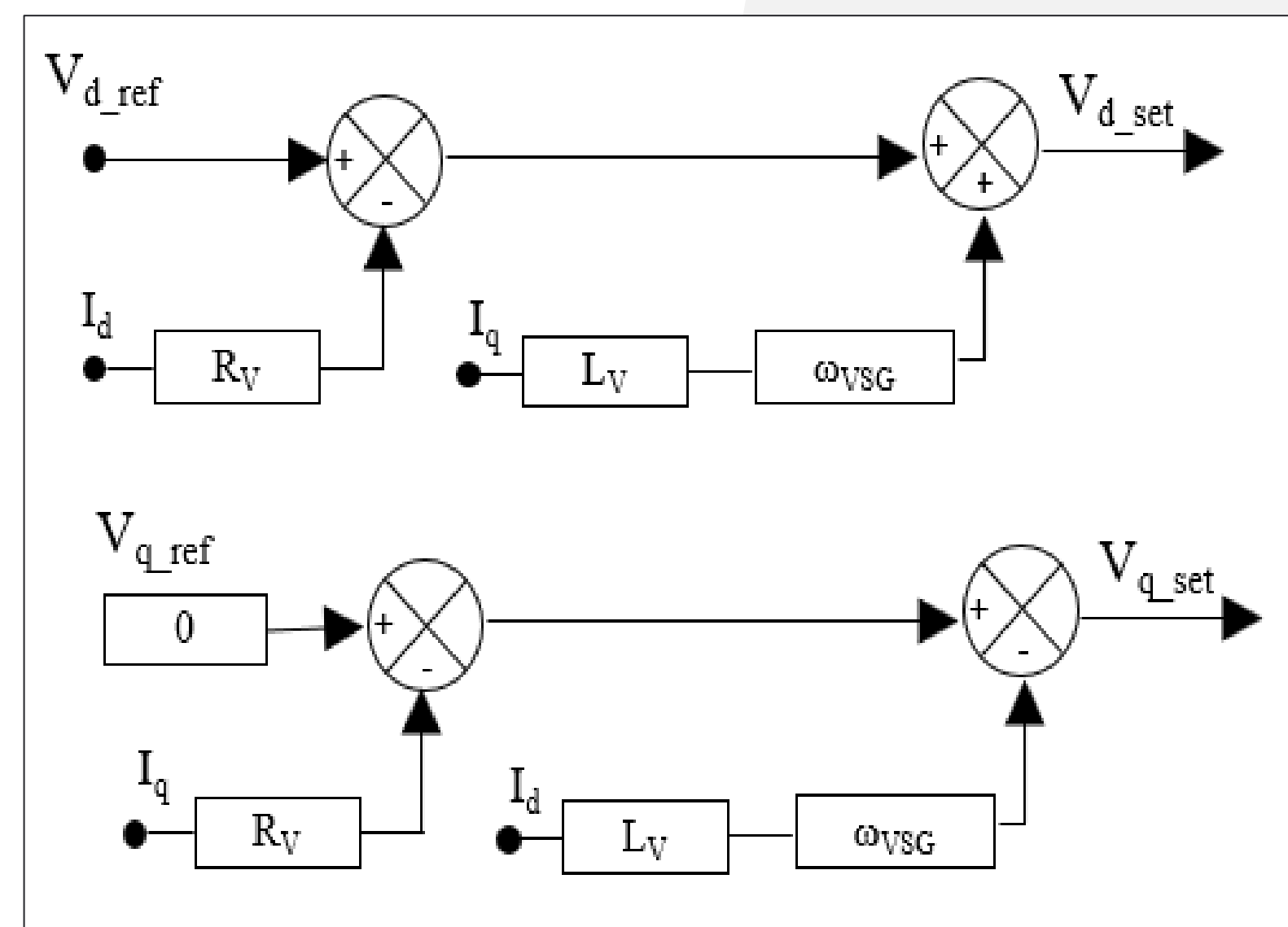
TaInertia time constant
KdDamping constant
Kw....Frequency droop constant

Outer loop:
Terminal voltage Controller

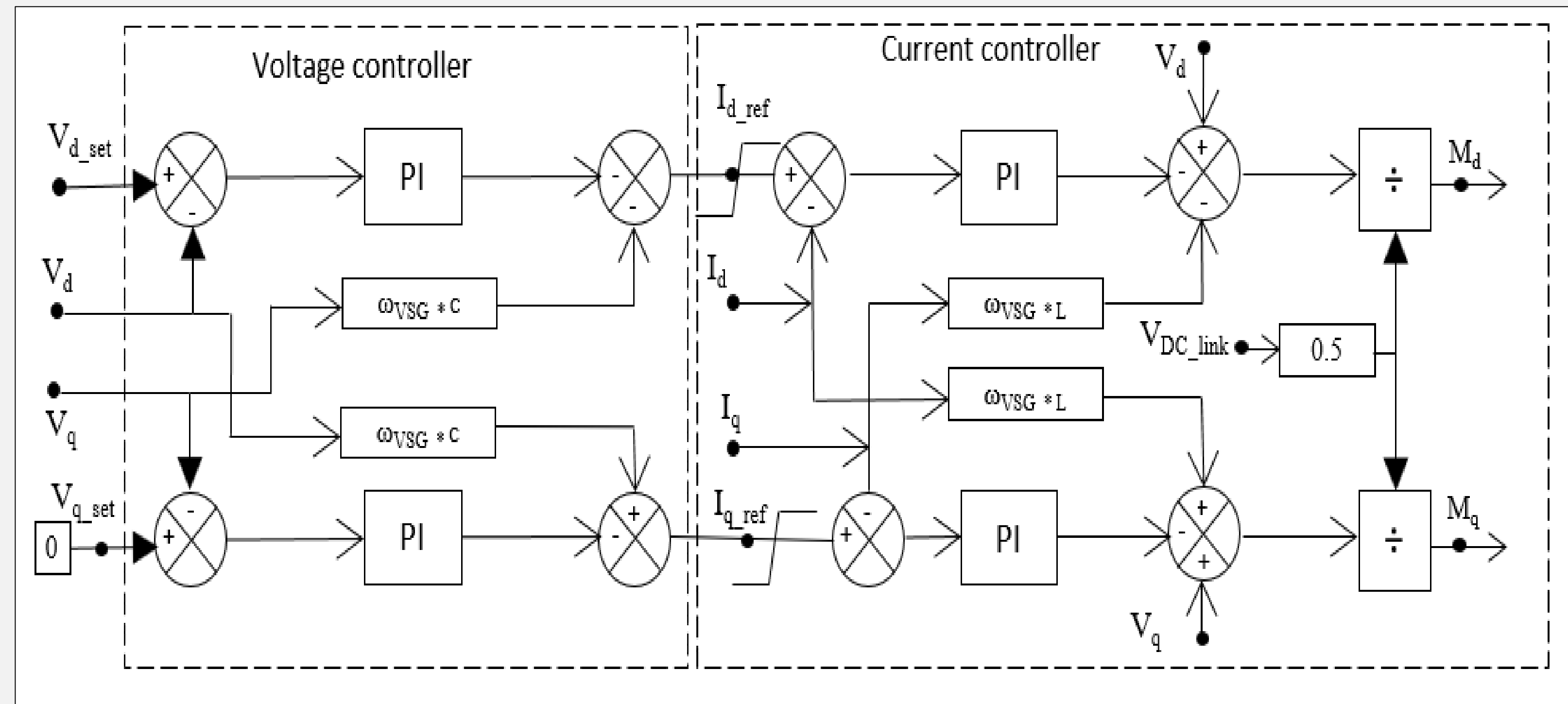


DC-AC converter controller

Inner loops



Virtual impedance



Cascaded voltage and current control loops

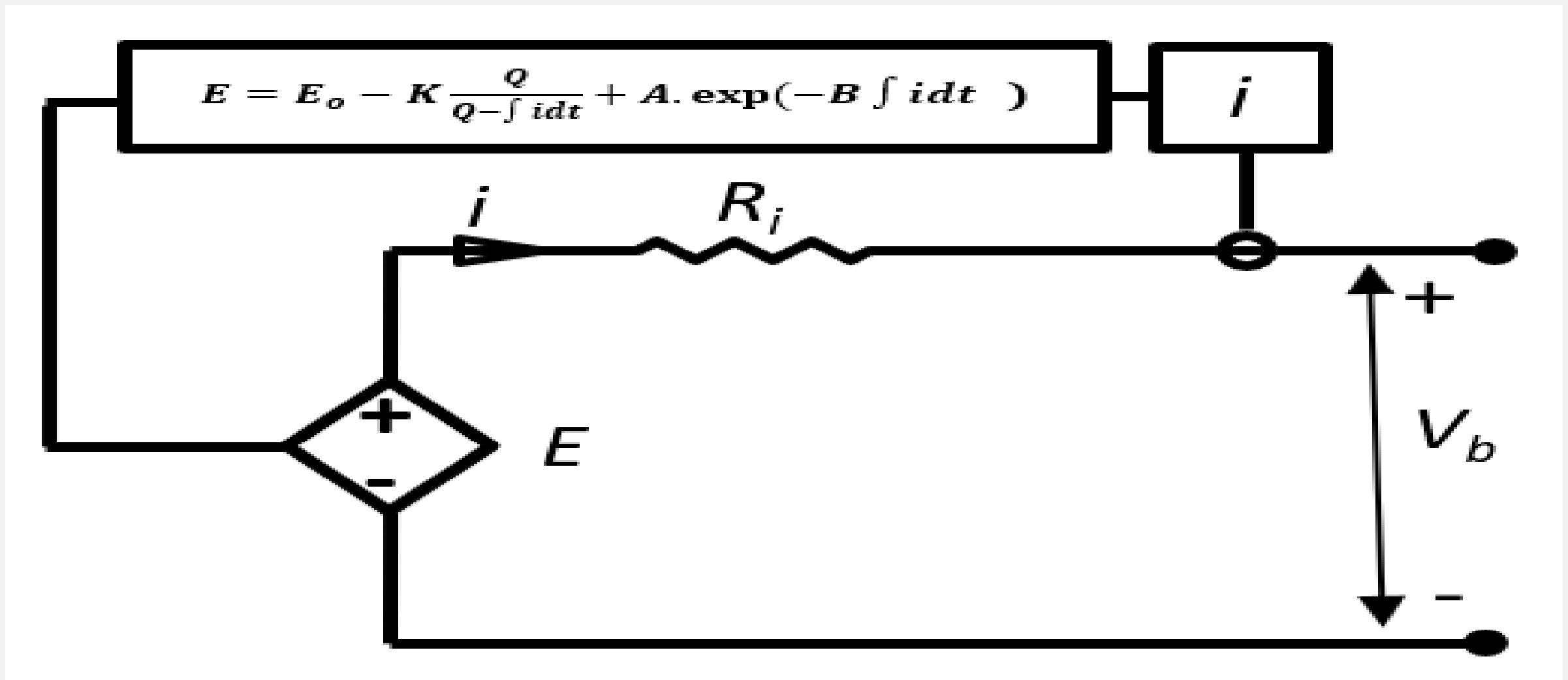
Battery storage system and dc-dc converter

The equivalent electric circuit model is based on a non-linear equation and the battery is modeled using a controlled voltage source connected with a series resistance.

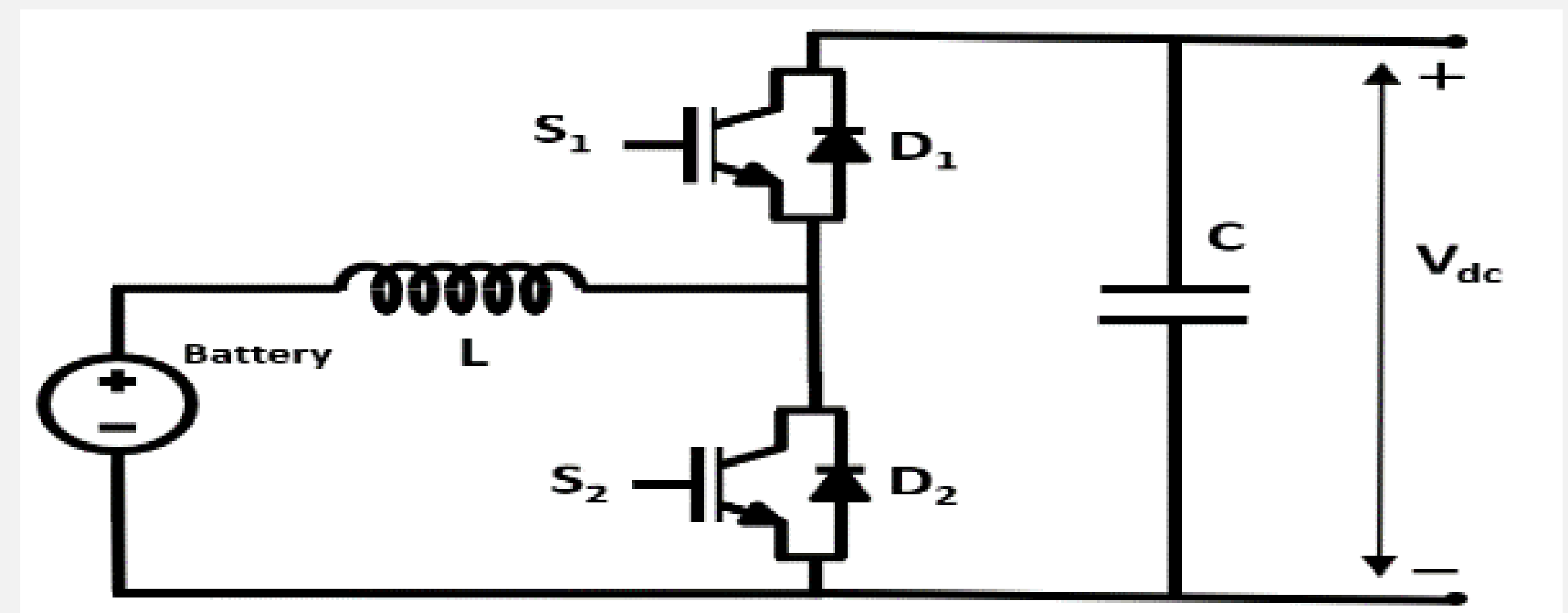
$$E = E_0 - K \left(\frac{Q}{Q - \int i dt} \right) + A * e^{-B \int i dt}$$

$$V_b = E - R_i * i$$

Battery Buck–Boost Converter controller

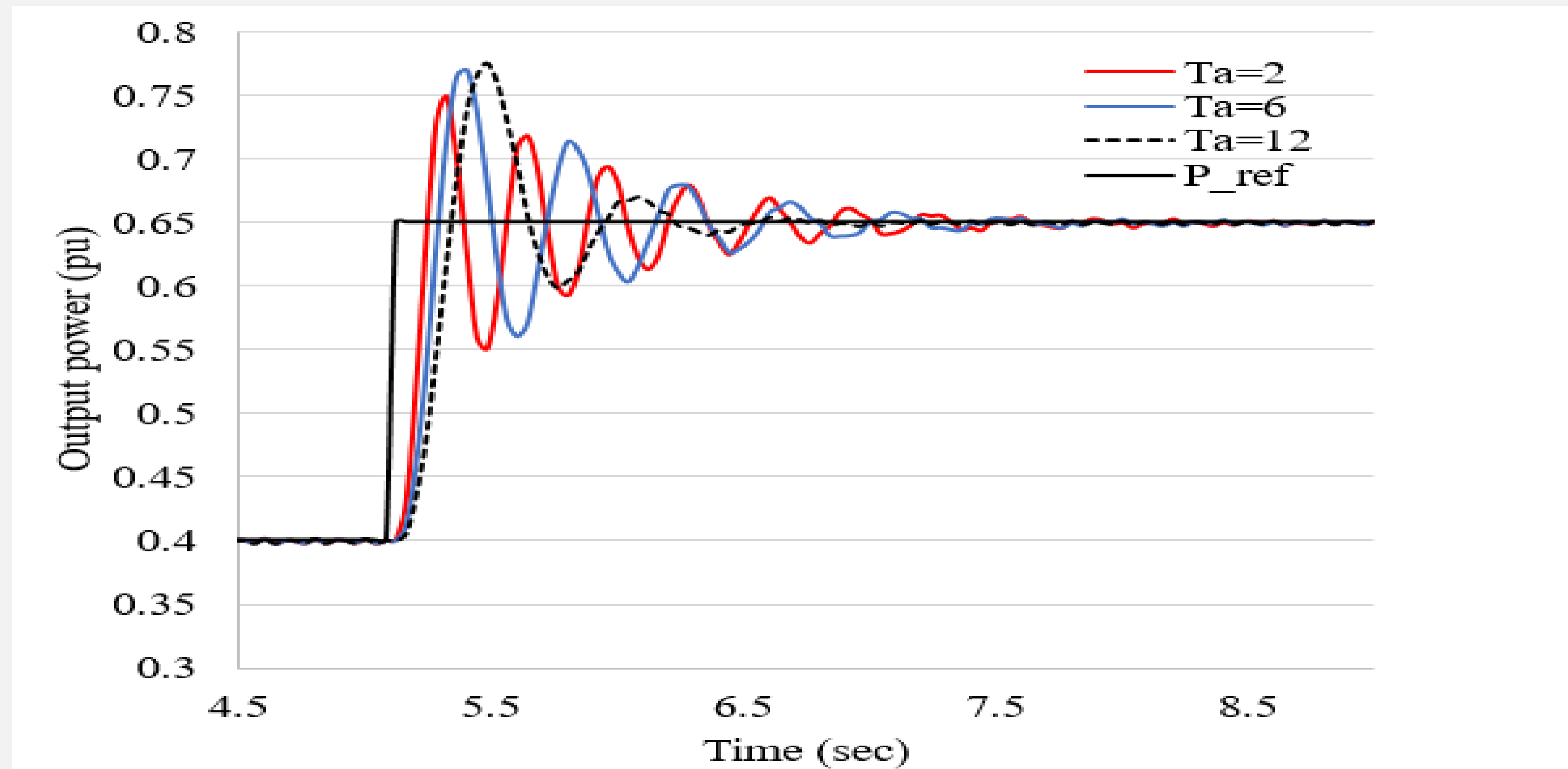


Battery equivalent electric circuit model



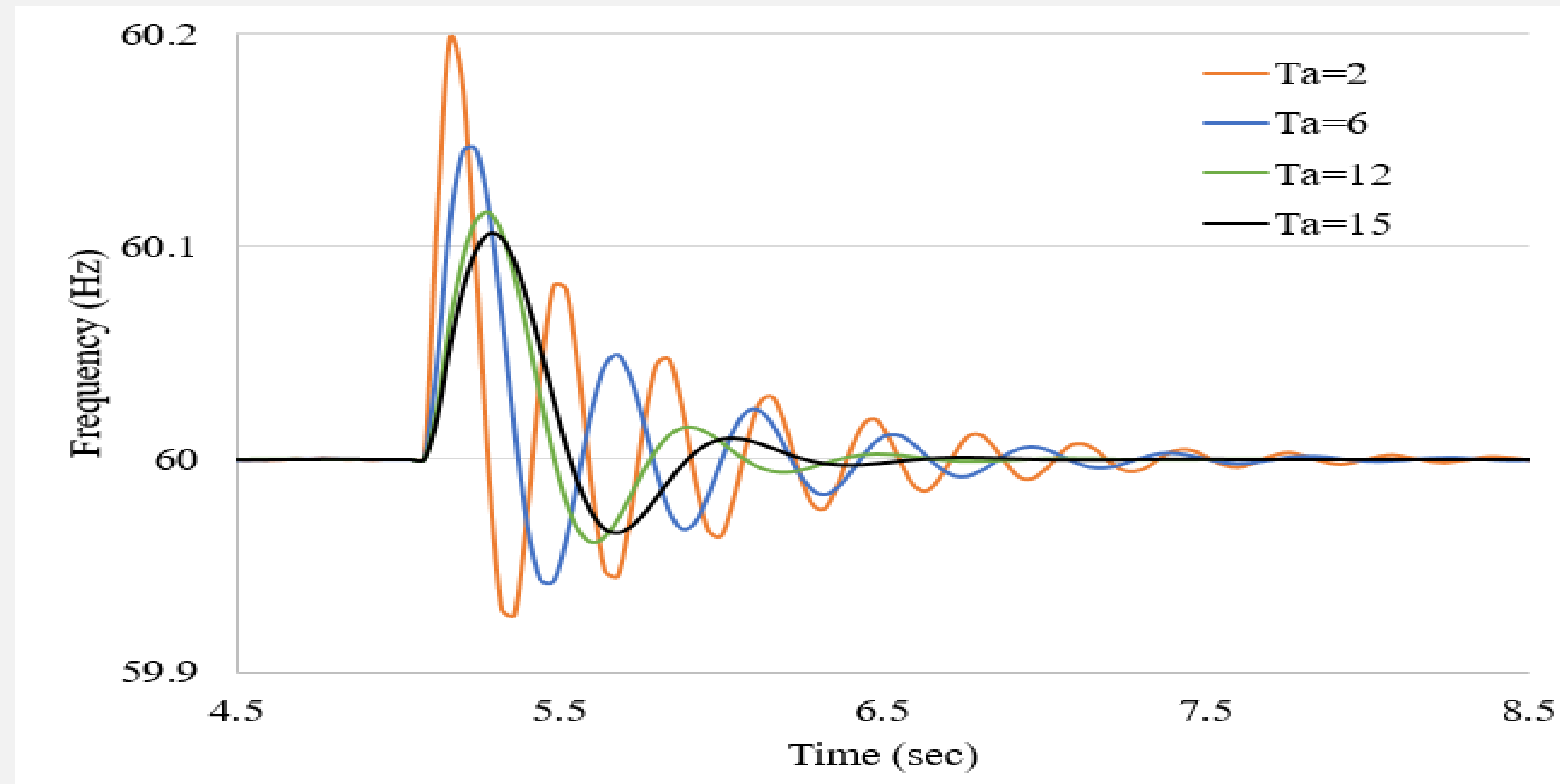
Battery Buck–Boost converter controller

Simulation results:
step power setpoint increase at different inertia time constant



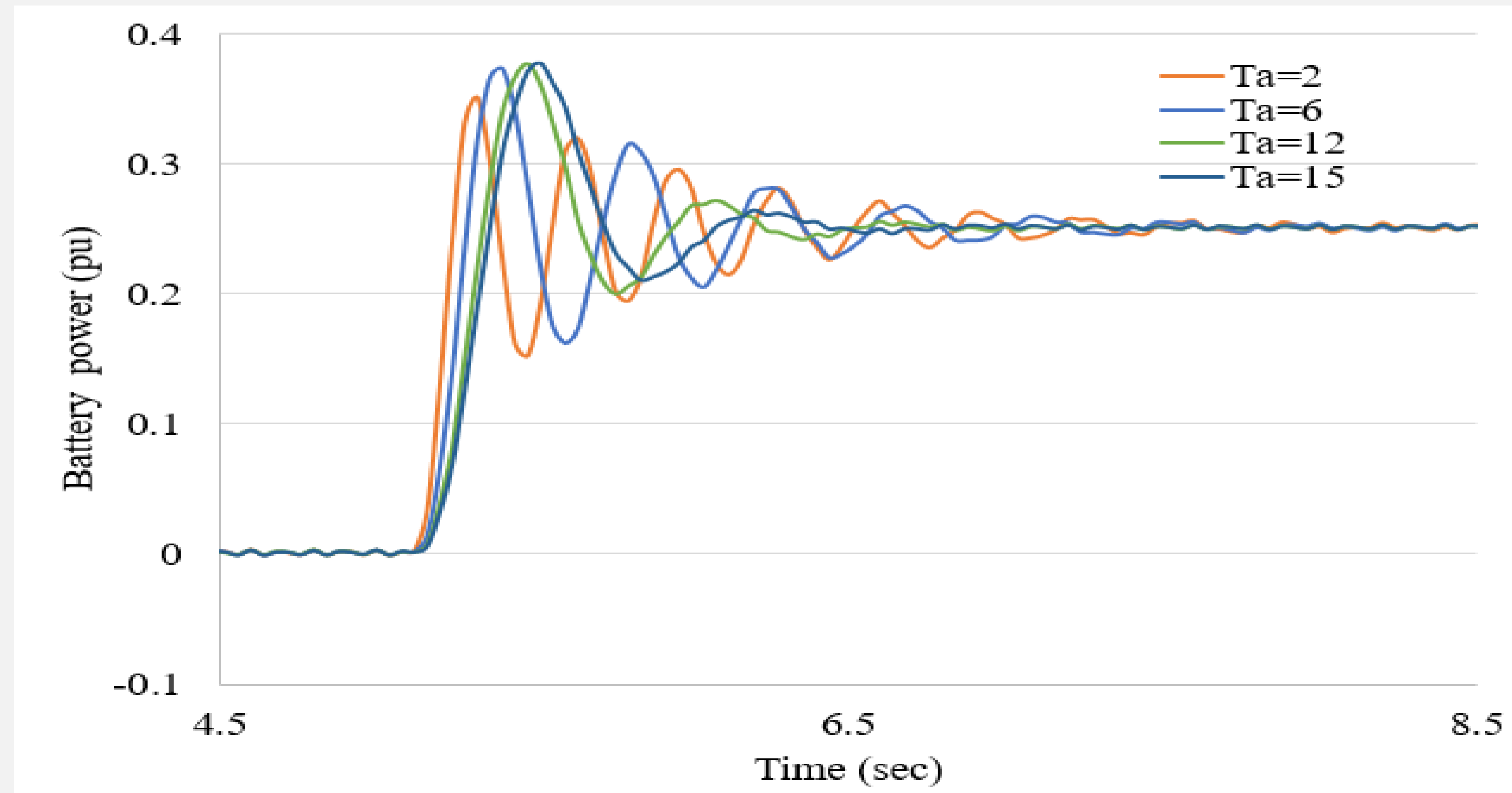
VSG converter active power variation at different inertia time constants ($K_d=0.16$)

Simulation results: step power setpoint increase



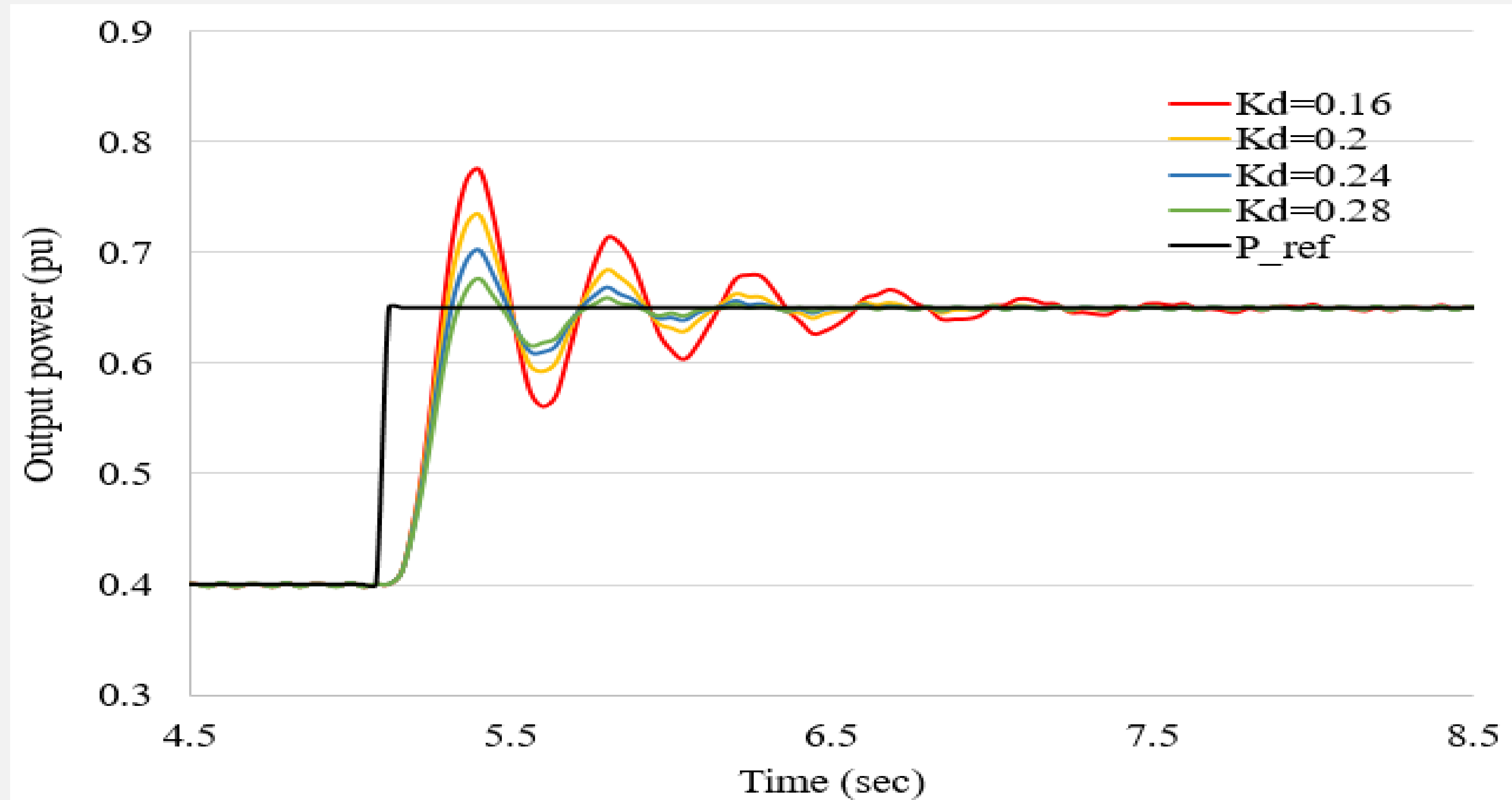
Frequency profile at different inertia time constants ($K_d=0.16$)

Simulation results: step power setpoint increase



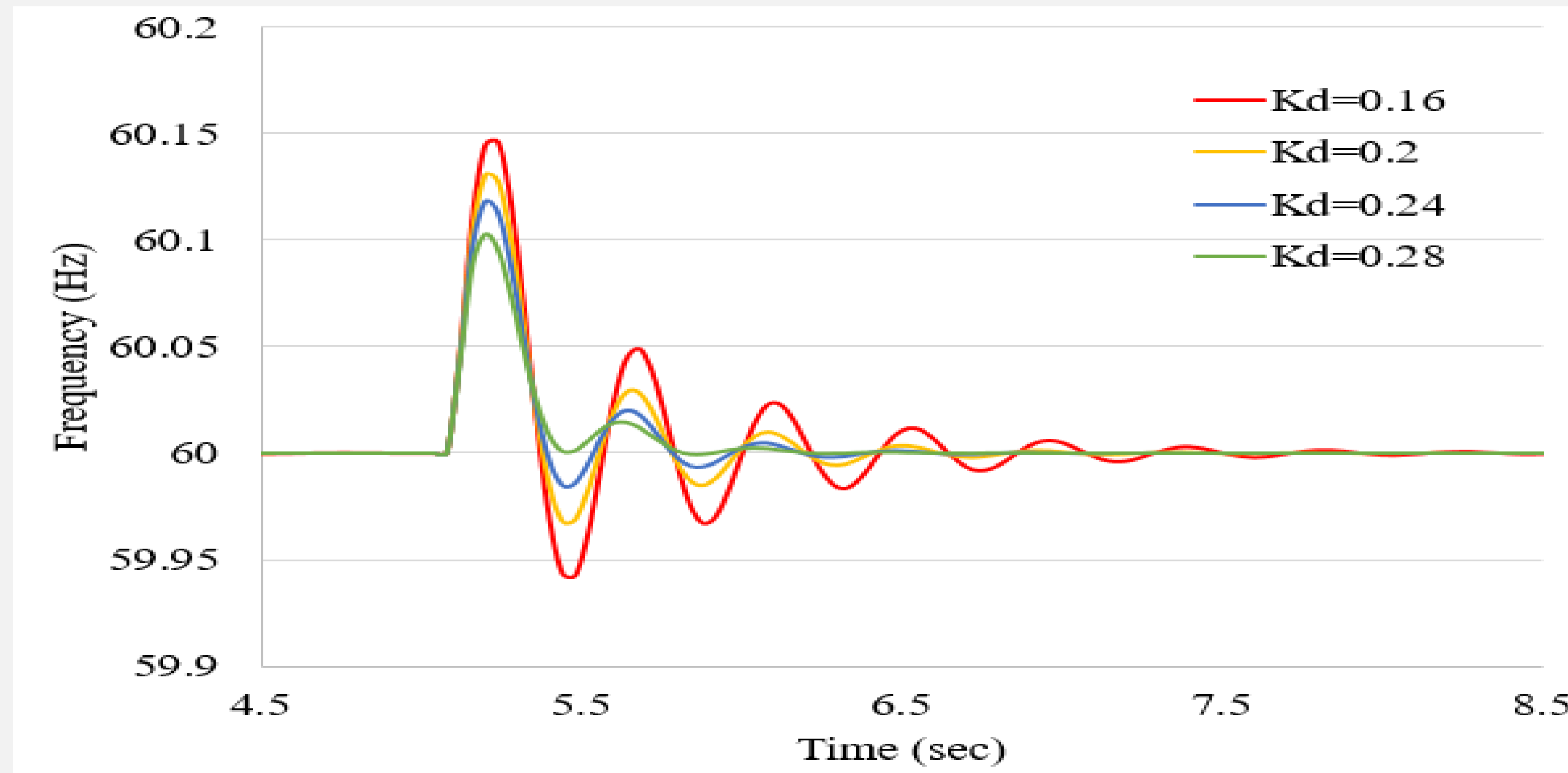
Battery power at different inertia time constants ($K_d=0.16$)

Simulation results: step power setpoint increase



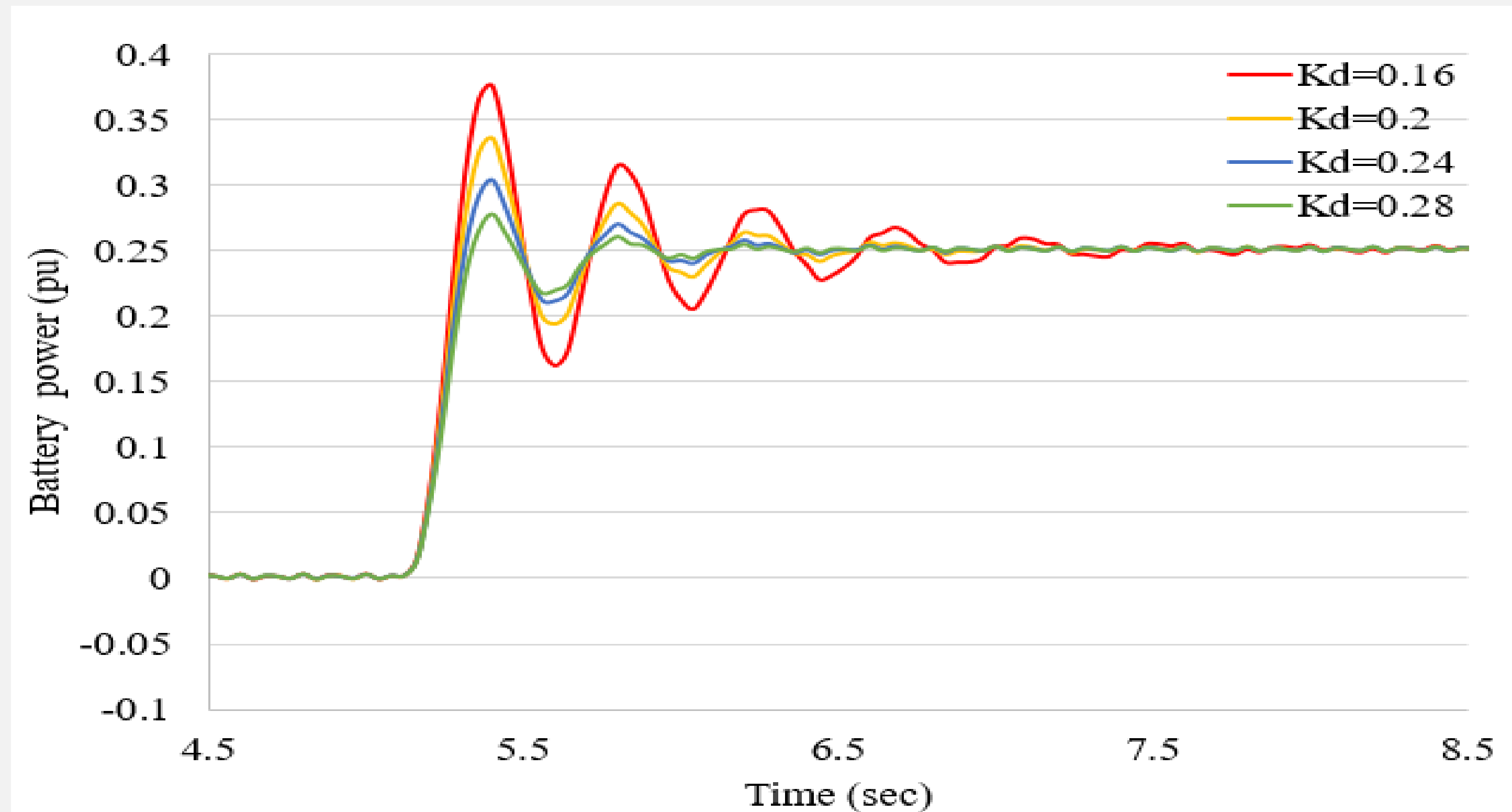
VSG converter active power variation at different damping constants ($T_a=6$)

Simulation results: step power setpoint increase



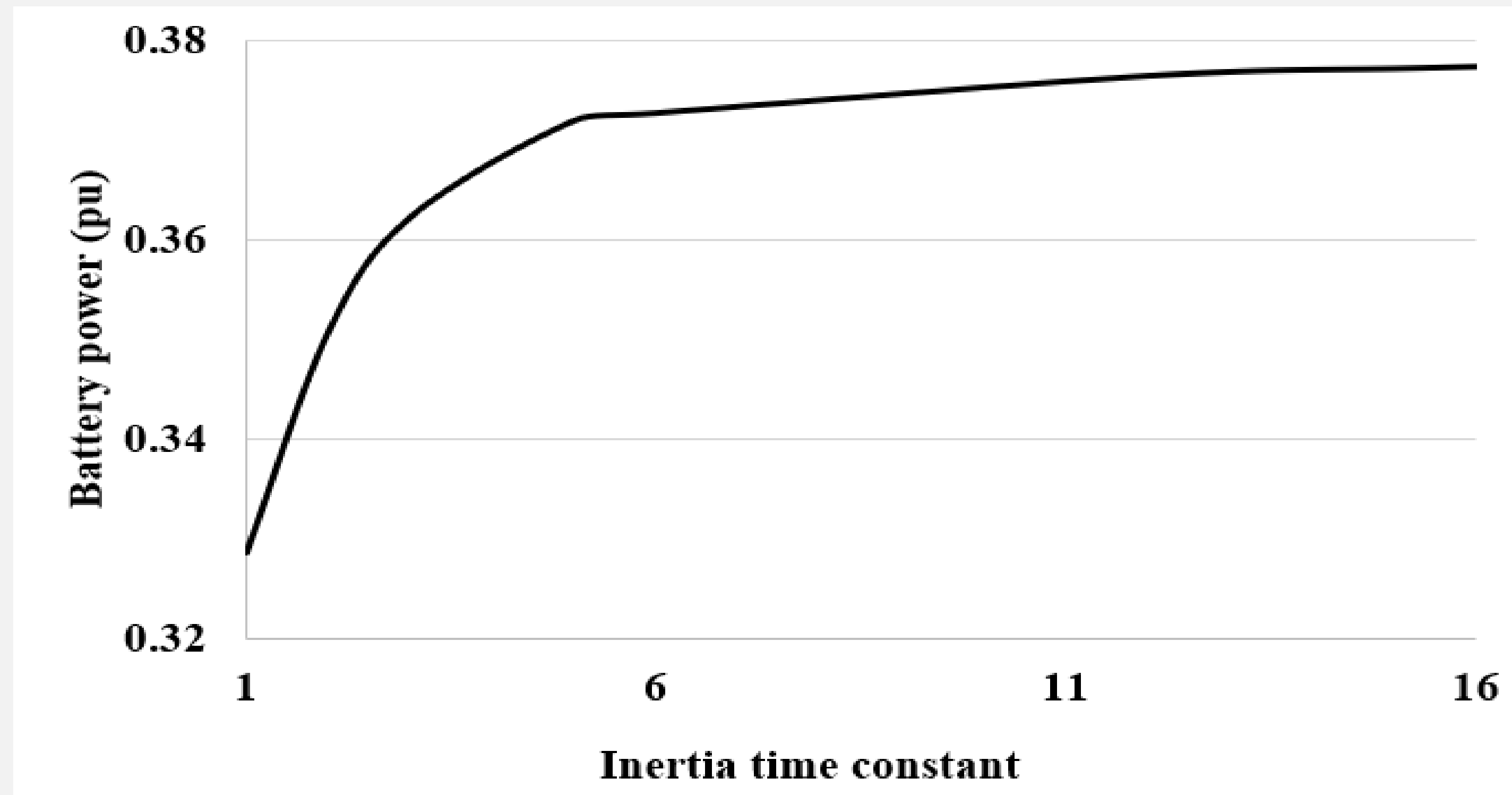
Frequency profile at different damping constants ($T_a=6$)

Simulation results: step power setpoint increase



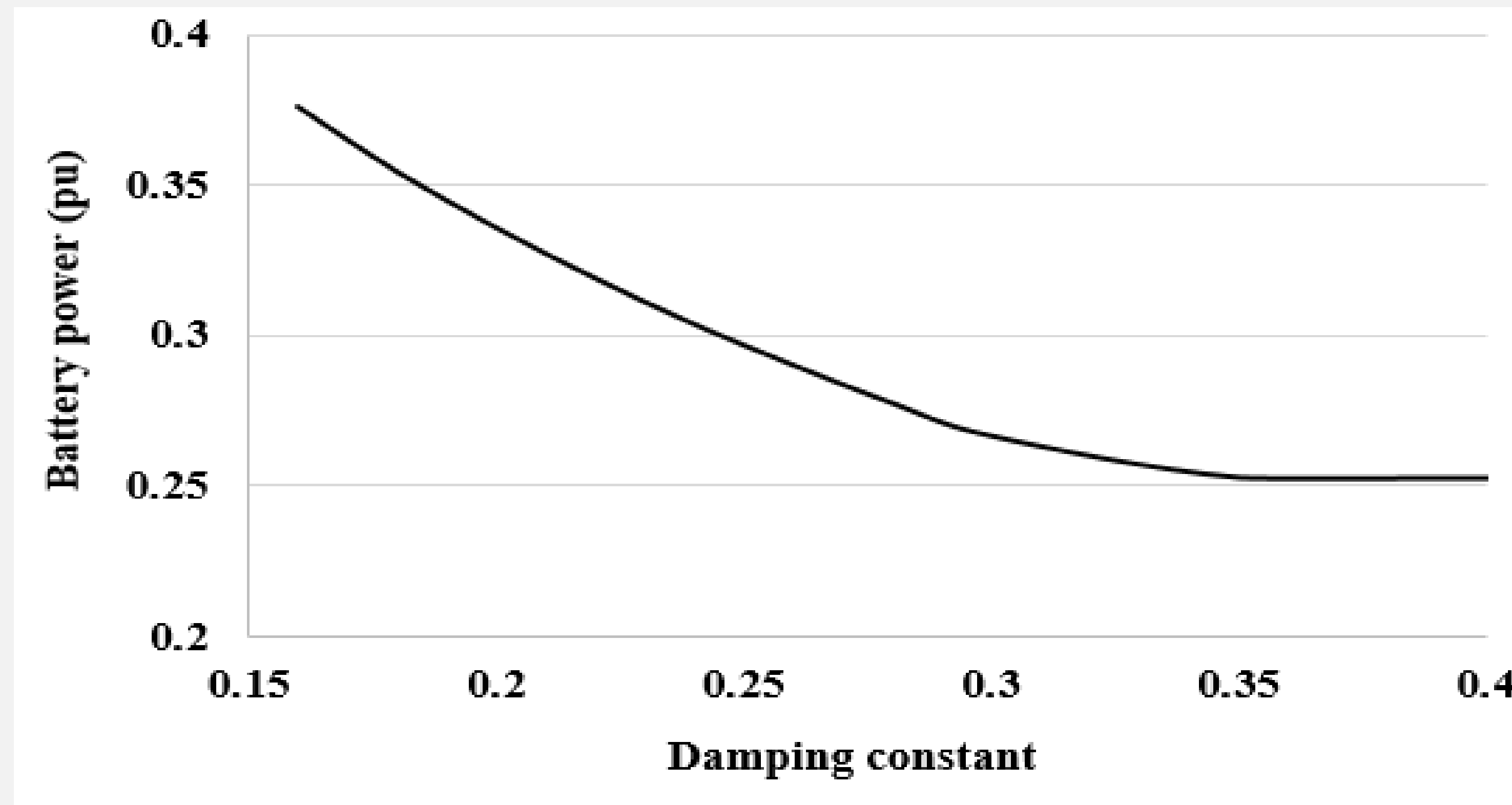
Battery power at different damping constants ($T_a=6$)

Simulation results: step power setpoint increase



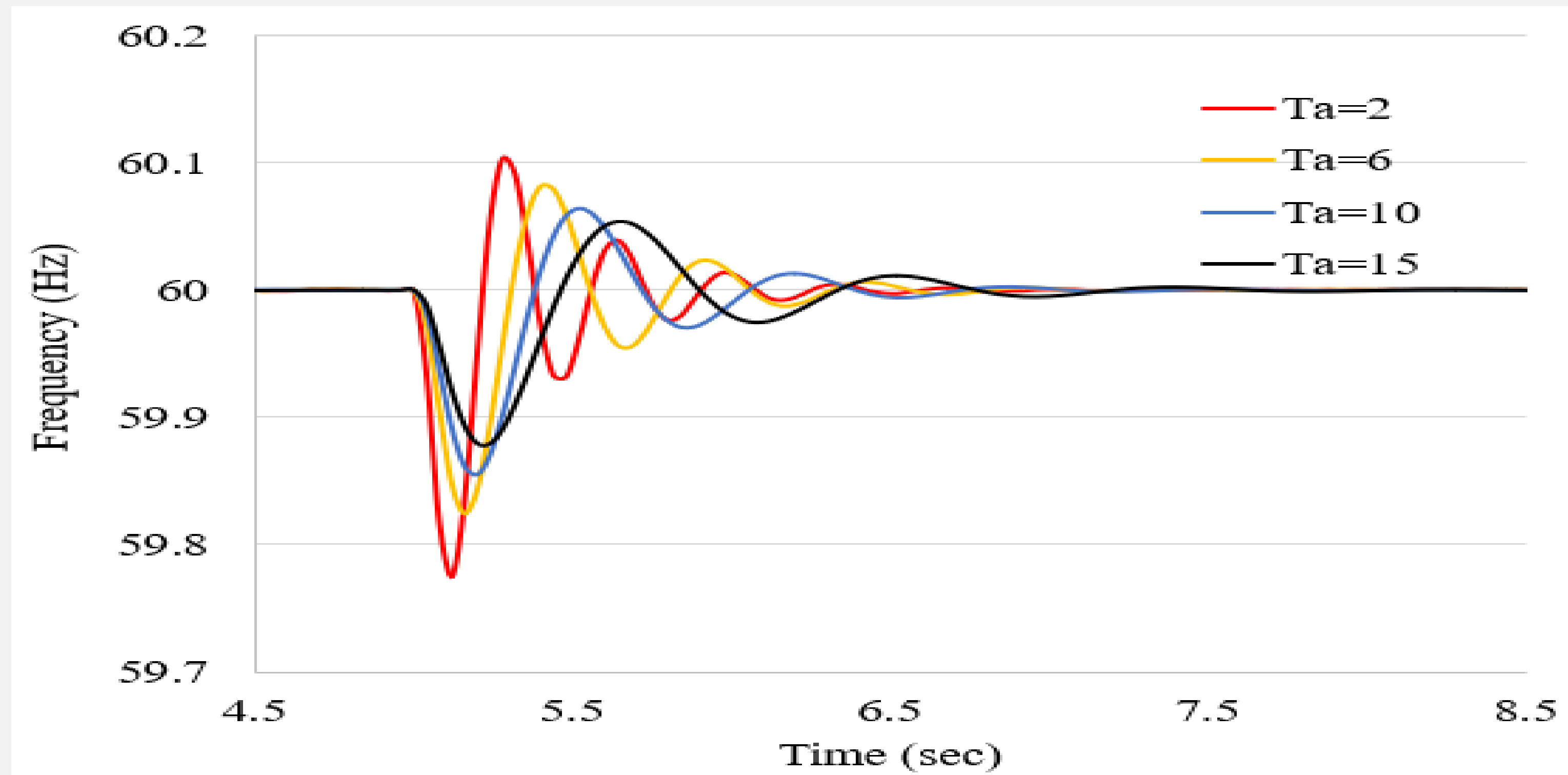
Battery generated power variation with respect to the inertia time constant

Simulation results: step power setpoint increase



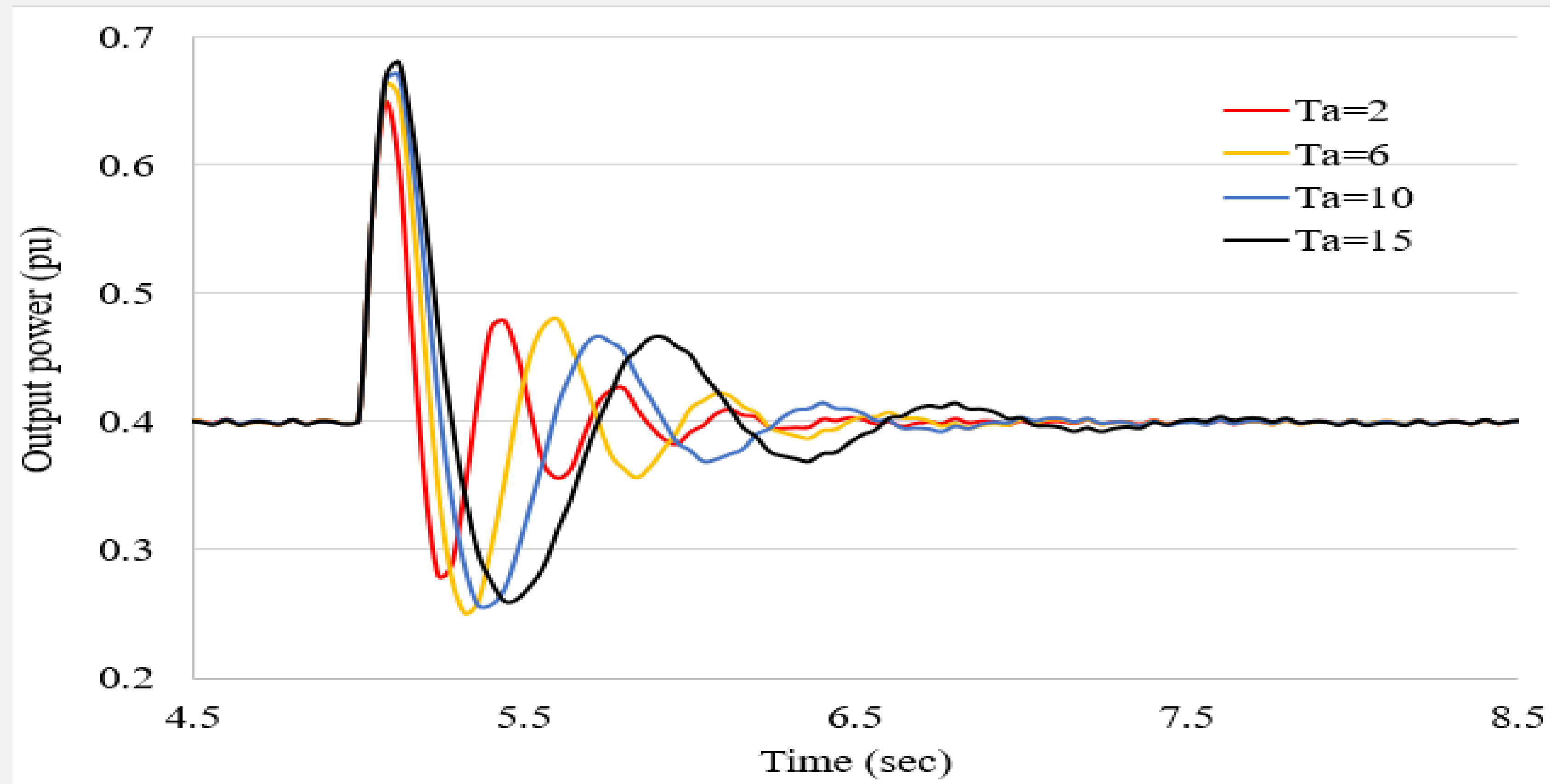
Battery power variation with respect to damping constant

Simulation results: sudden increase in load



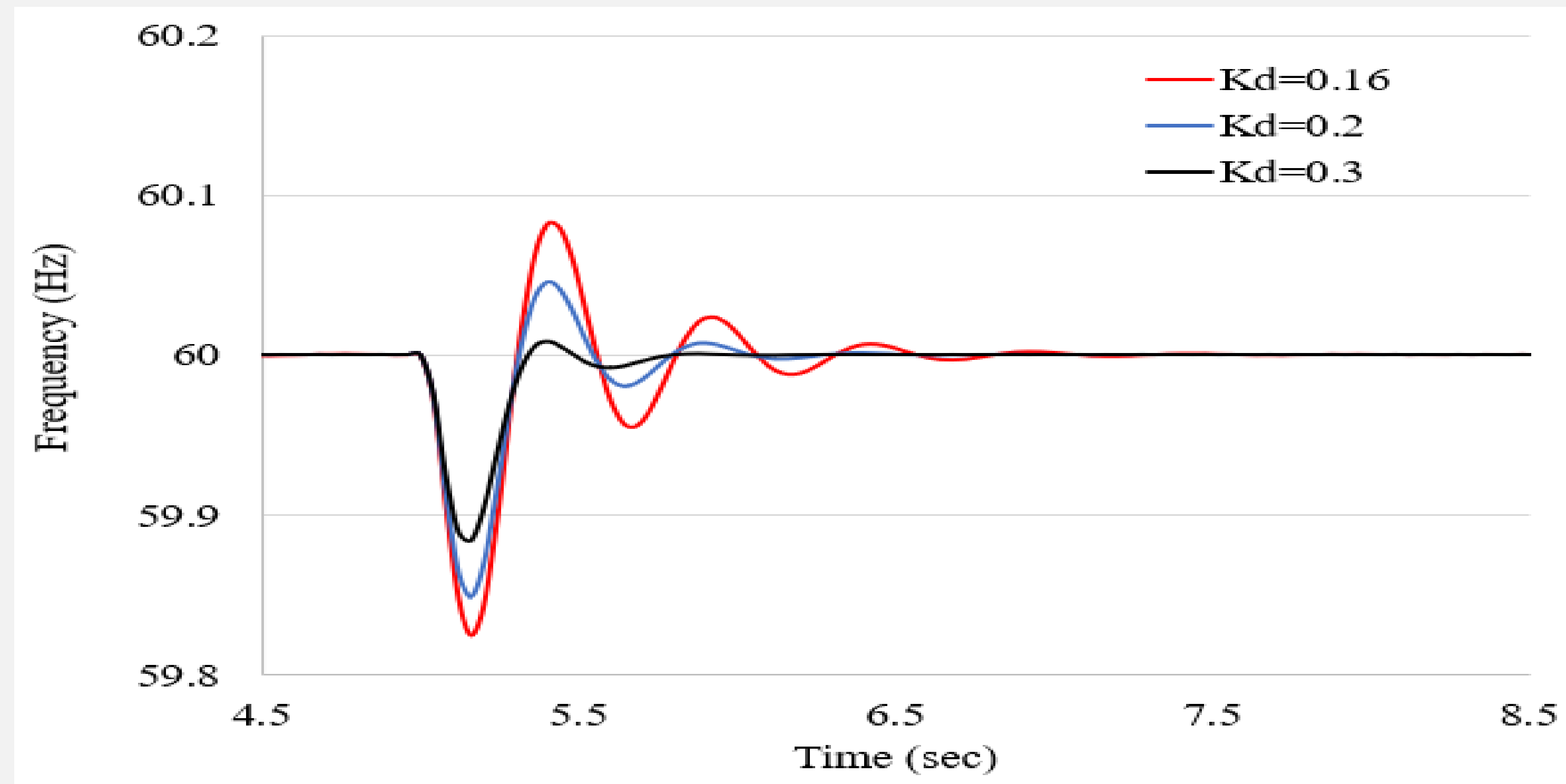
Frequency profile at different inertia time constants ($K_d=0.16$)

Simulation results: sudden increase in load



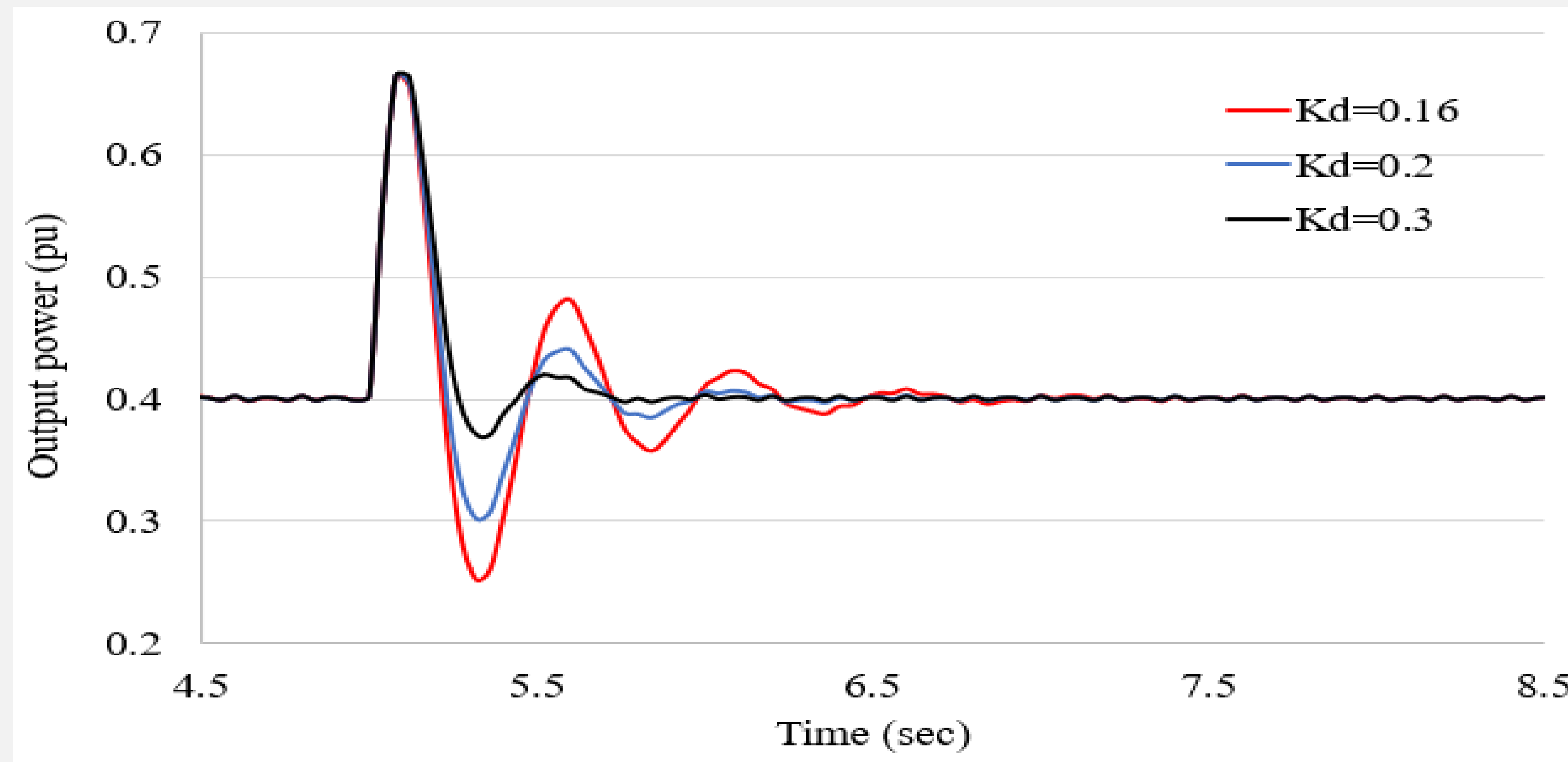
VSG active power variation at different inertia time constants ($K_d=0.16$)

Simulation results: sudden increase in load



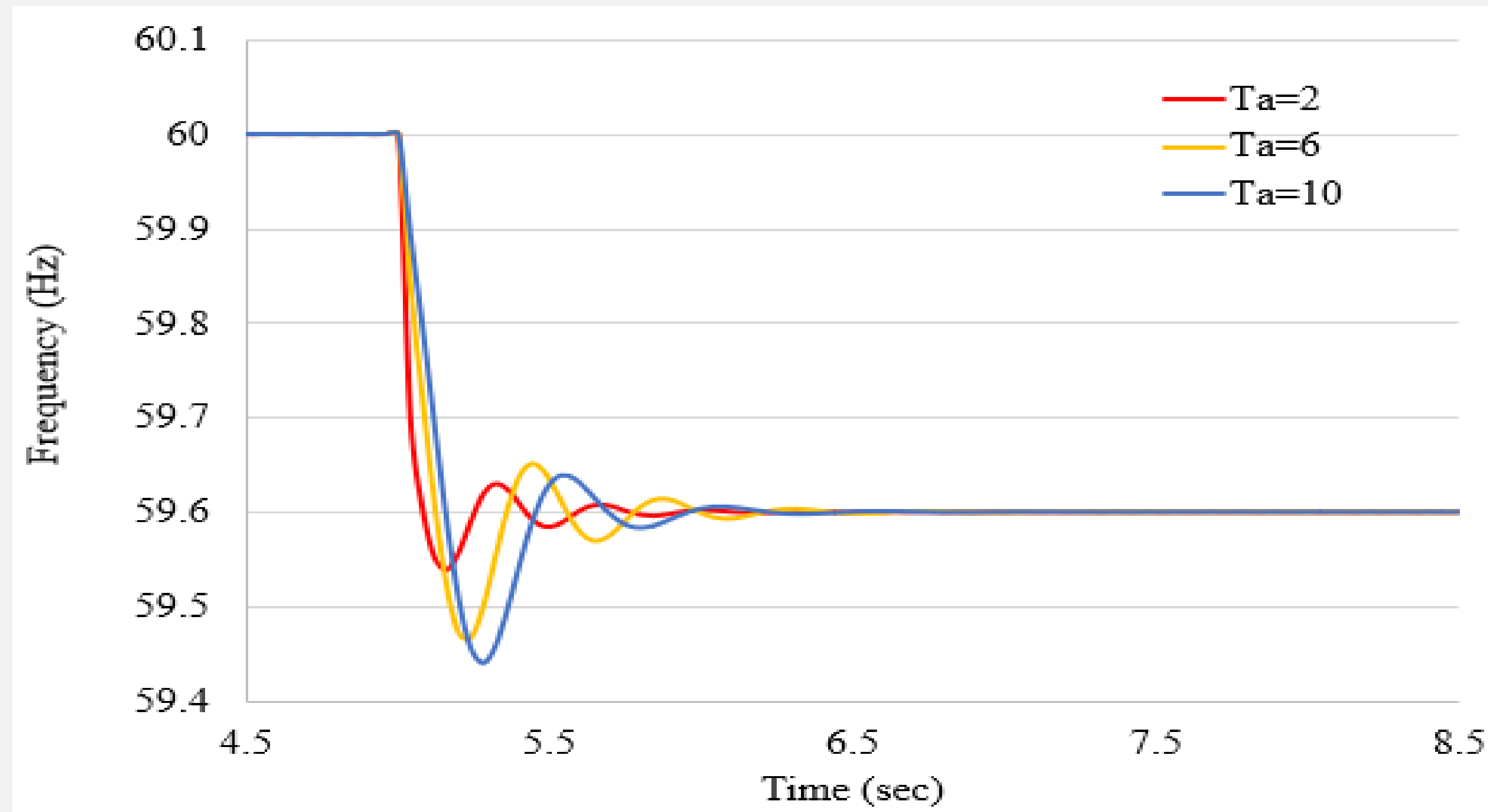
Frequency profile at step increase in load ($T_a=6$)

Simulation results: sudden increase in load



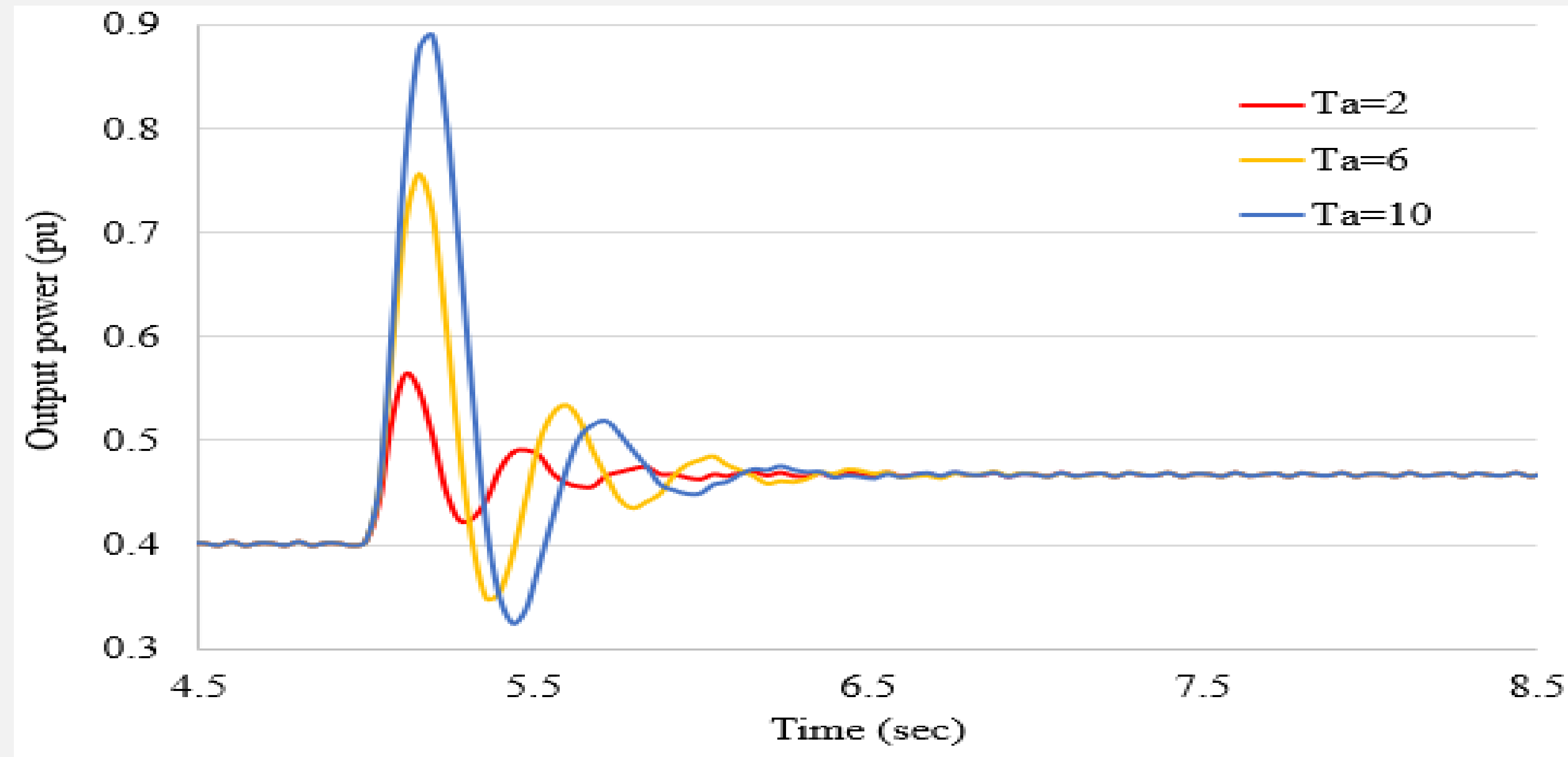
Output power profile at step increase in load ($T_a=6$)

Simulation results: microgrid frequency change



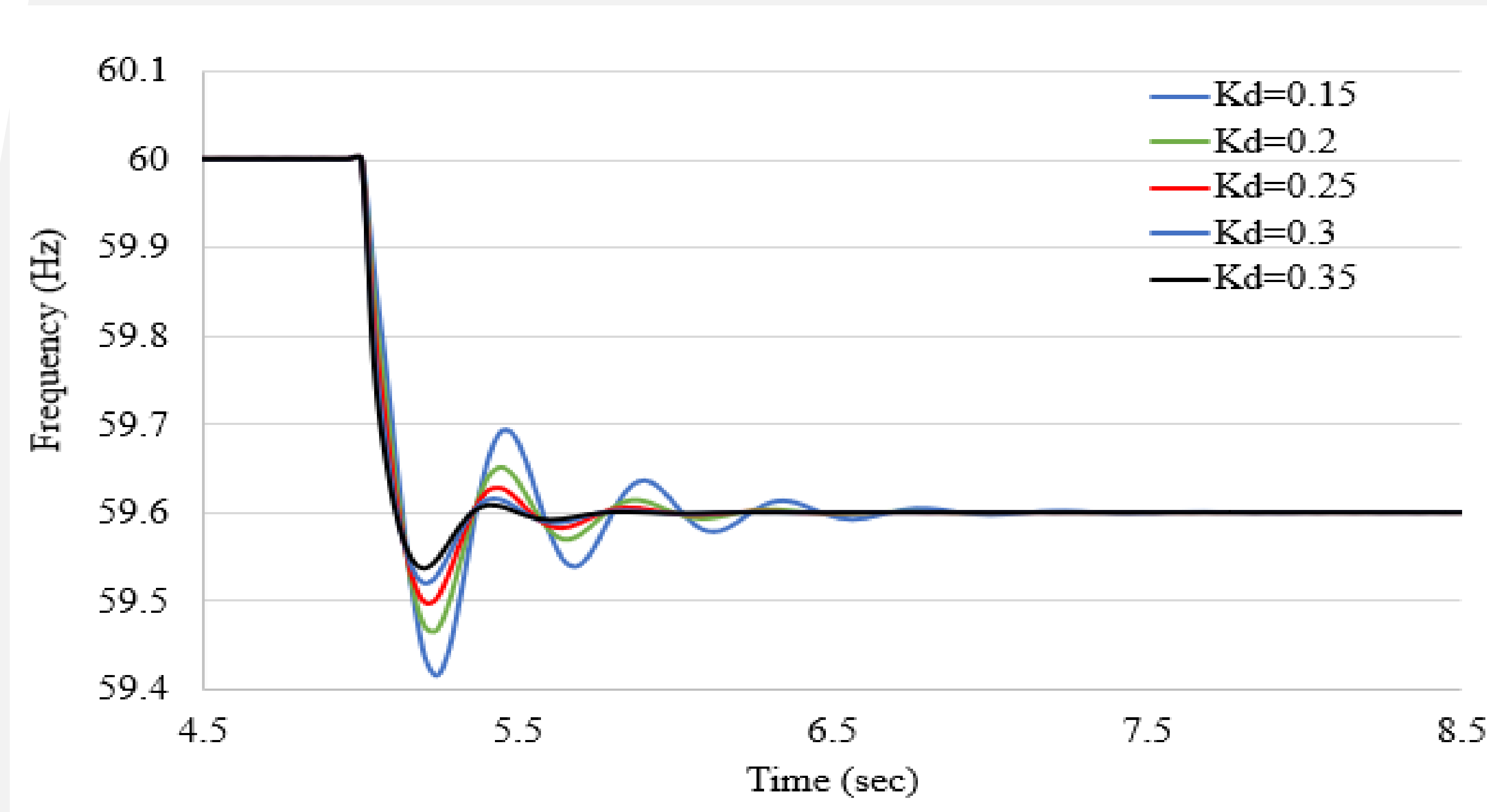
VSG frequency change in response to a microgrid frequency change ($K_d=0.2$)

Simulation results: microgrid frequency change



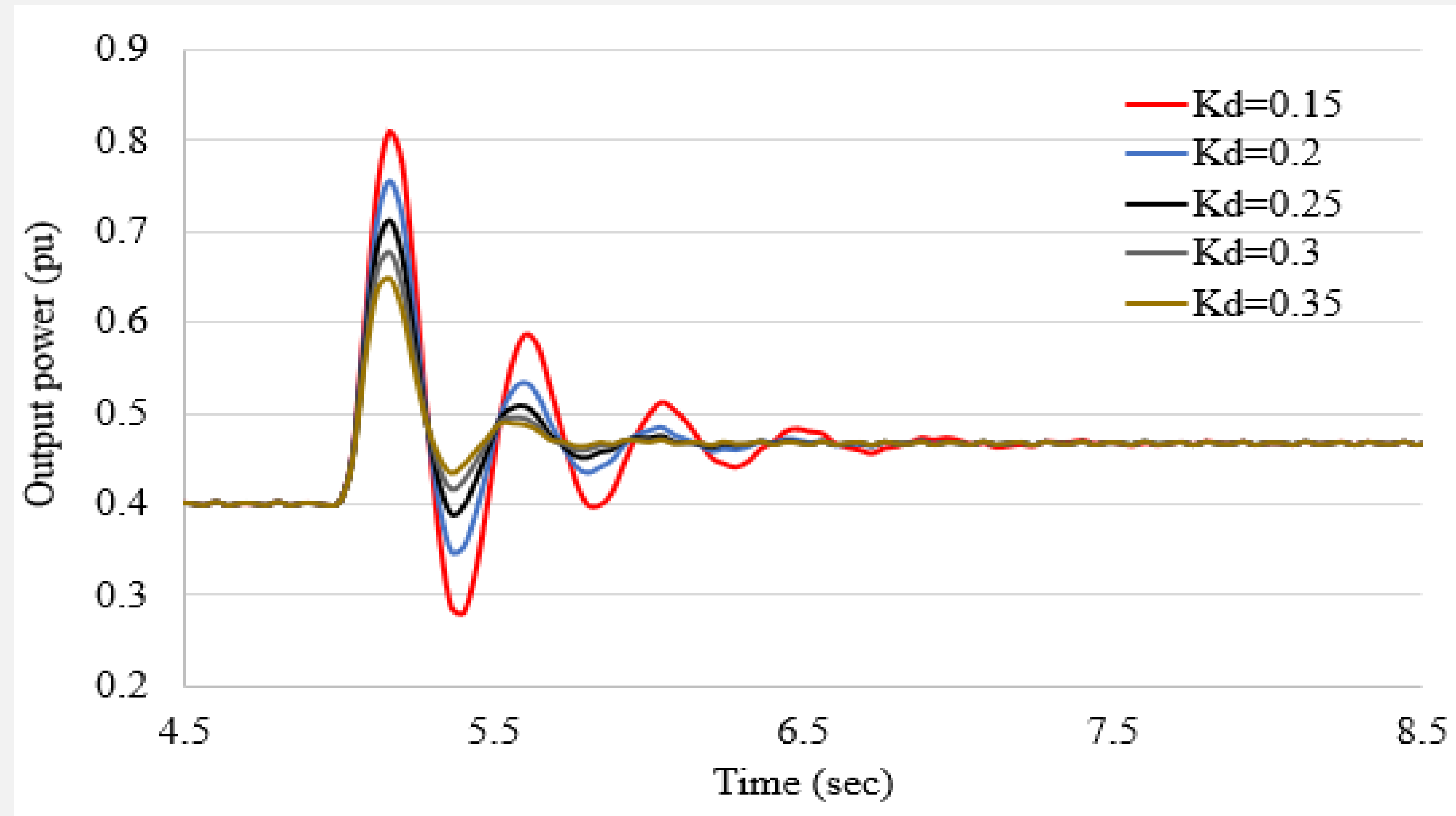
Output power in response to a microgrid frequency change ($K_d=0.2$)

Simulation results: microgrid frequency change



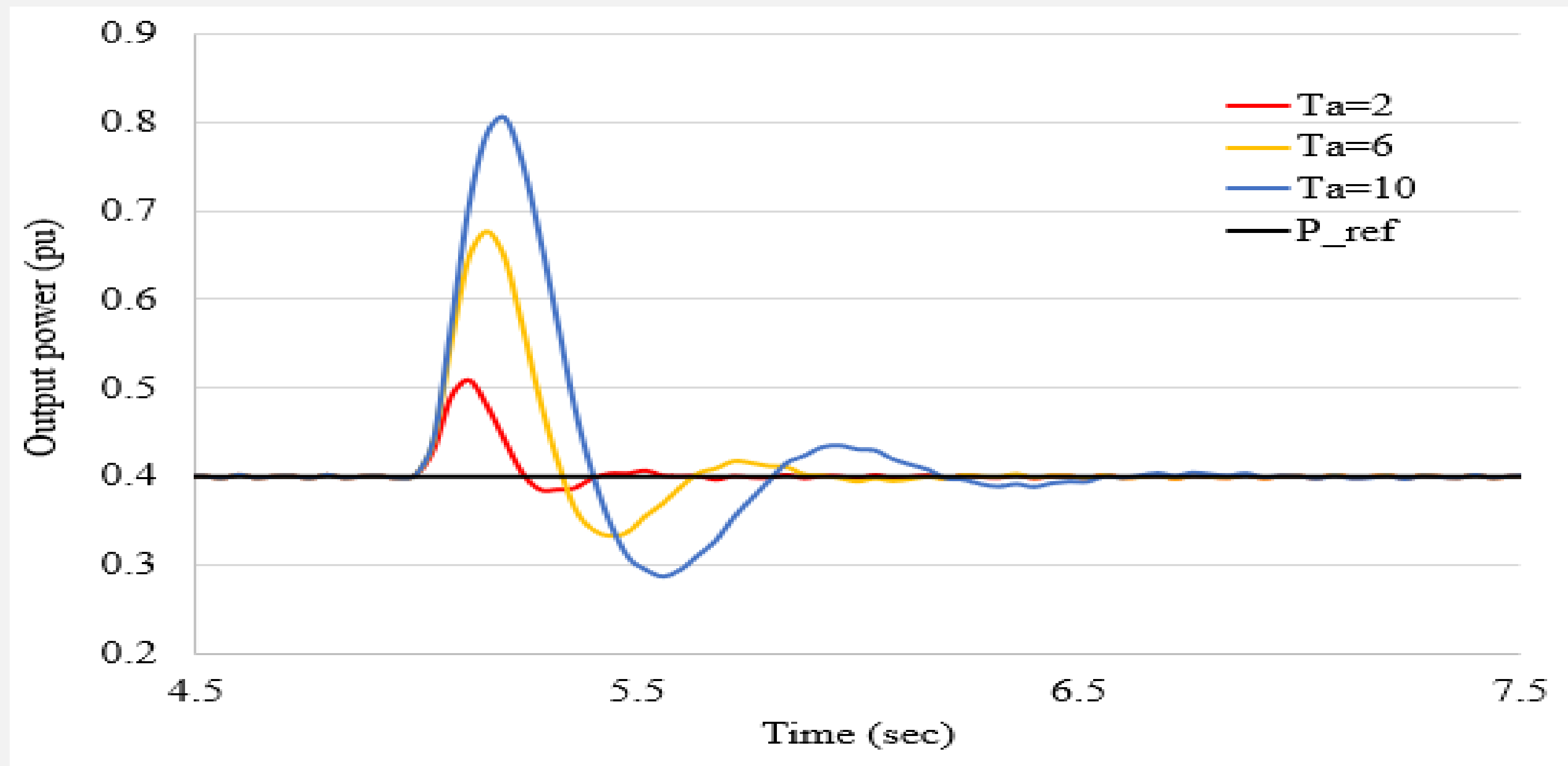
VSG frequency change in response to a microgrid frequency change ($T_a=6$)

Simulation results: microgrid frequency change



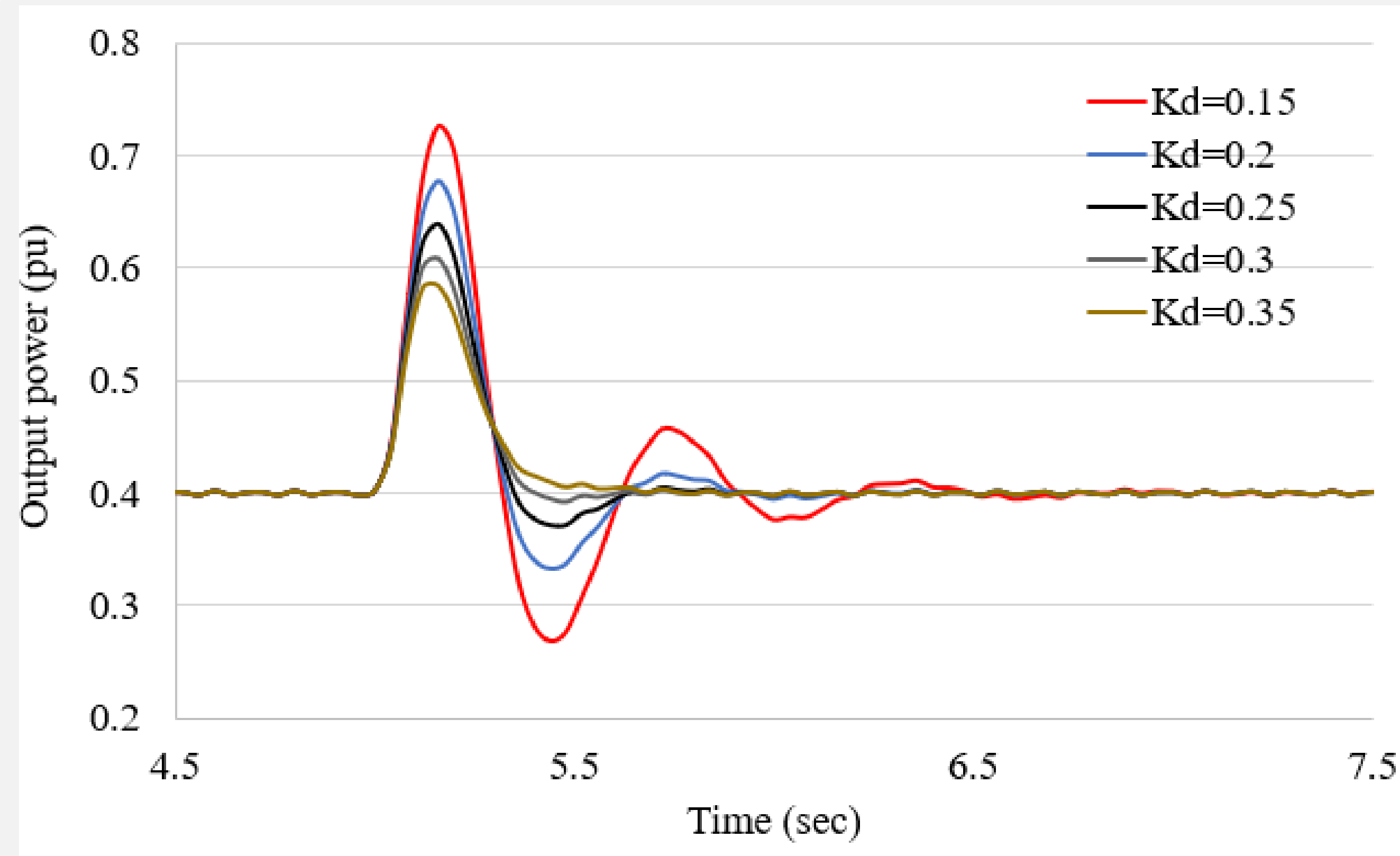
Output power in response to a microgrid frequency change ($T_a=6$), ($K_w=0$)

Simulation results: microgrid frequency change



Output power in response to a microgrid frequency change ($K_d=0.2$), ($K_w=0$)

Simulation results: microgrid frequency change



Output power in response to a microgrid frequency change ($T_a=6$)

Conclusion

- I Frequency fluctuation depend on the rotor inertia and damping constants.
- I VSG controlled based grid forming converter combined with ESS can emulate CSG's behavior.
- I VSG parameters can be changed to mimic the inertial features of many CSG
- I VSG supports the system frequency and improve its performance (RoCoF and frequency nadir).
- I The impact of different values of constants affect the ratings of the converter and the ESS.
- I The converter and the ESS power and energy increase when the inertia time constant increases
- I The converter and the ESS power and energy increase when the damping constant decreases
- I VSG controllers can promote expanding RERs in the power grids.



THANK YOU FOR ATTENTION

QUESTIONS

For any questions, please contact me at:
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