

# Generator Capability Envelope and Design Challenges to Accommodate Grid Code Requirements

2<sup>nd</sup> November 2016

Kevin Chan GE Power

Robert Cummings NERC

Kevin Mayor GE Power

John Yagielski GE Power



#### Introduction

- Synchronous generators are designed according IEC60034 and IEEE C50.13 standards.
- In a deregulated electricity market varying interests of the market players demand clear connection requirements in order to ensure the stability of supply
   defined in Grid Codes.
- All Grid Codes extend the technical requirements of equipment. Grid codes are not harmonized.
- Large scale integration of renewable energy sources leads to further flexibility requirements for conventional plants.



#### Change

#### **Affected Grid Performance**

**Generation Mix** 

New Technologies

System Inertia

Short Circuit Level

Conventional
Generator
Closures &
Increase in DG

Series
Compensation
& New CSC
HVDC Links

New VSC HVDC Links RoCoF

Frequency Containment
Generation Withstand Capability

System Stability

Protection

Voltage Dips

Voltage Management

Resonance and Harmonics

Emergency Restoration
System Inertia and Short Circuit
Level

Subsynchronous Resonance

**Control Systems** 

Image From National Grid System Operability Framework 2014



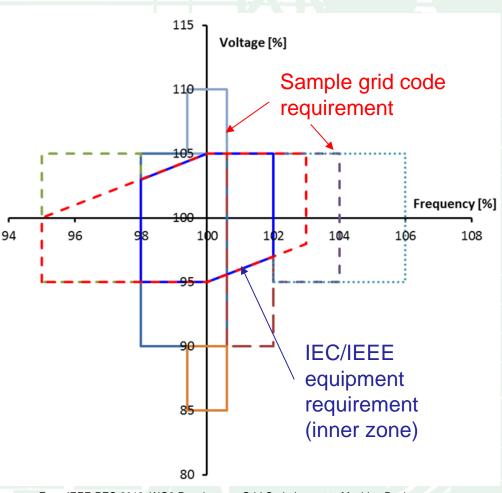
# **Typical Grid Code Requirements**

- Voltage-frequency operating ranges and durations
- Reactive power capability
- Generator short-circuit ratio (SCR)
- Rate of Change of Frequency (RoCoF) withstand
- Fault ride through
- Excitation voltage ceiling factor
- Auto-reclosing
- Power output Vs Frequency



# Voltage-Frequency Operating Range

- V-f ranges often significantly larger than in equipment standards
- Boundary conditions are often not defined (e.g. reactive load, duration of disturbance, frequency of occurrence)
- Voltage ranges usually defined for connection point → For OEM unclear without knowing:
  - Transformer reactance
  - Use of on-load tap changer (OLTC) transformer



From IEEE-PES-2012\_WG8-Panel-paper\_Grid Code Impact to Machine Design



# V-F Range Design Challenges

- V-f requirements not harmonized between grid codes
  - Difficult to design standard generators for standard turbines (engineering/manufacturing effort → cost impact)
- Enlarged V-f ranges lead to oversized machines (cost impact)

#### • Possible solutions:

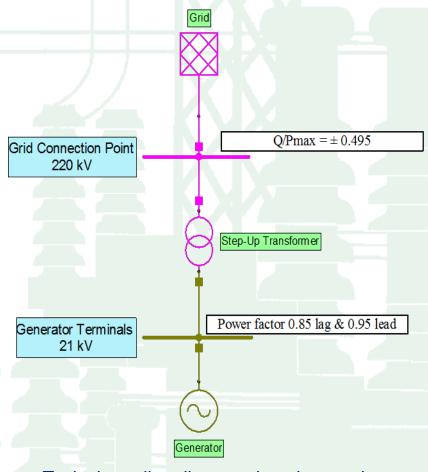
- Clear definition of operating conditions, expected duration and frequency of occurance of voltagefrequency excursions by TSO's
- Equipment standards to allow short-term overheating during short term voltage and frequency excursions



## **Reactive Power Capability**

#### **Existing Equipment Standards:**

- MVAr capability defined by standard rated power factors at the generator terminals of 0.8, 0.85 and 0.9 overexcited.
- The lower the power factor the larger will be the machine. →
   Do not over-specify
- Recommended: Grid codes to specify 0.95 underexcited power factor at rated MW, consistent with equipment standards.



Typical one-line diagram denoting varying locations for capability requirements



# MVAr Capability Design Challenges

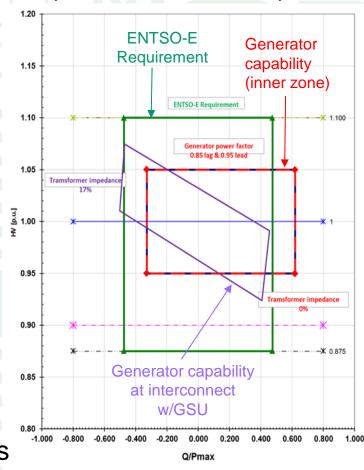
#### **Grid Codes:**

- MVAr capability is often defined at grid connection point by Voltage vs. Q/P<sub>max</sub> diagrams
  - → Capability depends on generator AND step-up transformer design
- Without OLTC transformers, conventionally designed synchronous machines can hardly meet the requirements:
  - → oversized, more expensive generators

#### Possible solutions:

- TSO's to allow OLTC in all transmission grids
- Grid codes to consider requirements at generator terminals and harmonize with realistic V-f-MVAr conditions

#### Comparison of V vs Q/Pmax requirements





# **Short-Circuit Ratio (SCR)**

#### IEC 60034-3 / IEEE C50.13 specifies a minimum SCR of 0.35:

- Most generators designed to have SCR > 0.45
- Most grid codes require SCR ≥ 0.5
- A high SCR is believed to improve grid stability
- Marginal improvement with SCR=0.5 compared with SCR=0.45
  - Insignificant difference with fast and high gain excitation systems
  - Increases generator size / cost & reduces efficiency
  - Effective only for certain grid configurations at the connection point

IEC60034-4 SCR definition:

$$SCR = K_c = \frac{i_{f0}}{i_{fk}}$$

 i<sub>f0</sub> ...field current at no-load and <u>rated</u> terminal voltage
 i<sub>fk</sub> ...field current at 3-phase short-circuit and <u>rated</u> stator current



# **SCR Design Considerations**

#### **Selection of Larger Generator**

 Weight increase ~0.6 times the percentage of SCR increase

• SCR: 0.45 → 0.5

⇒ Weight: 100% → 107%

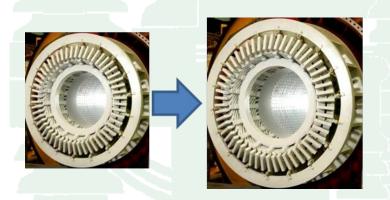
#### Air Gap Increase

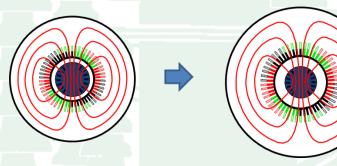
 Weight increase ~0.35 times the percentage of SCR increase

• SCR: 0.45 → 0.5

⇒ Weight 100% → 104%

 Field current increases with the air gap and leads to higher temperature and lower efficiency







# **SCR Design Considerations**

#### **Possible solutions:**

- Harmonization of grid code requirements for countries with similar grid topology (SCR ←→ reactive capability, V/f range)
- Flexibility of grid codes to allow lower SCR if grid study shows no significant benefit for stability
- Lower SCR requirements in grid codes for large generating units



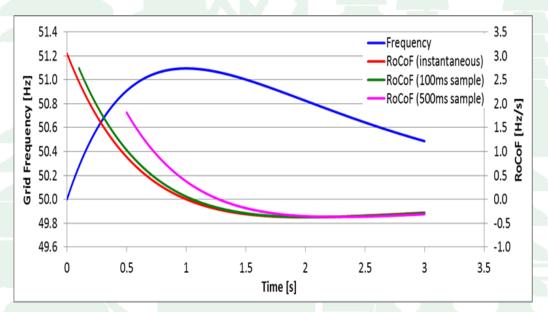
# Rate of Change of Frequency (RoCoF)

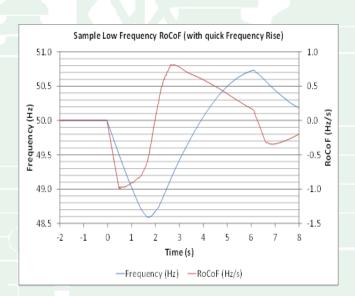
- Grid codes require Generators to stay connected during high gradients of grid frequency.
  - e.g.: Australian code requires up to 4Hz/s for up to 0.25s
- Usually only max. Gradients are defined, but boundary conditions are often unclear and do not allow an evaluation
- Generator standards do not specify RoCoF withstand capability



#### **RoCoF Requirements**

- Recommendation: Grid codes to define:
  - Expected duration of the event for the required RoCoF
  - Expected wave shape(s) of the frequency excursion (right diagram)
  - Measurement conditions for the RoCoF value (left diagram)





Variation in measured RoCoF based on sampling rate



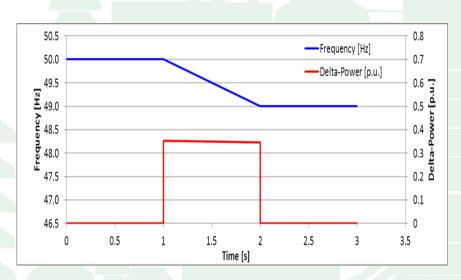
RoCoF general evaluation by simplified representation:

- Frequency changes with constant gradient
  - → immediate power step request at generator terminals.
- Step is deceleration or acceleration power of shaft line
- Negative frequency gradients are critical:
  - → generator load angle increase
  - → exported power increase

Result: new balance or pole slip.

Recommendation: Grid codes to allow for out-of-step protection

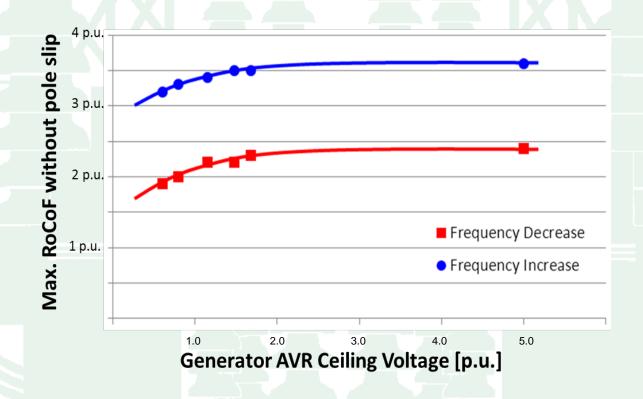
Rate of Change of Frequency	Resulting immediate Power Step $\Delta P$ (example, typical GT single drive shaft train)			
0.5 Hz/s	17.5 %			
1.0 Hz/s	35 %			
2.0 Hz/s	70 %			
3.0 Hz/s	105 %			
4.0 Hz/s	140 %			





# **RoCoF Design Challenges**

- Increased AVR ceiling voltage has limited effect on capability
- Above ceiling factors of 2, no significant increase in withstand capability

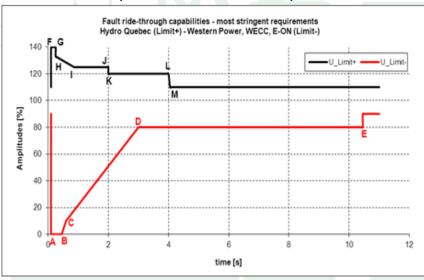




# Fault Ride Through (FRT) Capability

- Generators designed (per IEC60034-3 / IEEE C50.13) to withstand sudden short-circuits may not comply with FRT requirements.
- FRT capability depends on generator characteristics and external factors:
  - system pre and post fault conditions,
  - transformer reactance
  - → System studies necessary!
- Local grid codes give varying profiles
- FRT requirements may impact design parameters such as inertia, SCR, ceiling voltage, etc.
  - → Difficult to have a standard design

#### Representative FRT requirement



		LVRT			HVRT	
İ	Point	Time [s]	U <sub>PCC</sub> [%]	Point	Time [s]	U <sub>PCC</sub> [%]
	Α	0	0	F	0.1	140
	В	0.45	0	G	0.2	140
4	С	0.55	6.46	Н	0.25	133
	D	3.00	80	I	0.85	125
1	E	10.45	90	J	2.00	125
				K	2.05	120
(				L	4.00	120
4				M	4.05	110



# **Excitation Voltage Ceiling Factor (CF)**

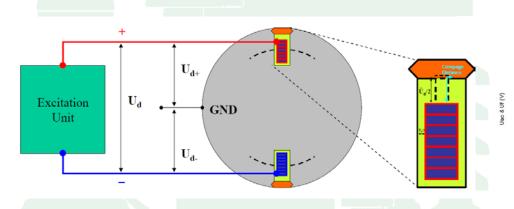
- One possibility for improved FRT capability is excitation system with a higher excitation voltage CF.
- IEEE 421.4 specifies a minimum excitation voltage CF of 1.5.
- Grid code requirements on voltage CF vary from 1.6 to 4.
   Current grid codes show tendency toward voltage CF ≥ 2.

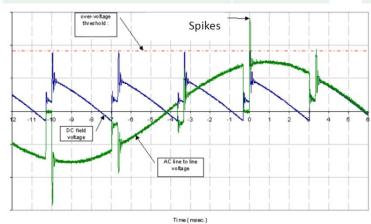


# Voltage CF Design Challenges

#### Consequences of high voltage CF:

- Rotor insulation systems are crucial to the reliability of a generator.
- High voltages impose additional duty on the field winding insulation system.
- The field winding is exposed to switching spikes that reach ceiling voltage several times per cycle and may exceed the allowable voltage level of the rotor winding insulation.





# Voltage CF Design Challenges

#### High excitation voltage:

- Higher pulse (12 or more) exciter to reduce over-voltages
  - → increased equipment costs.
  - → non industry standard solution.
  - → may require new development of converter bridges for large units.

#### Alternative to high excitation voltage:

- Separately sourced excitation system → increased equipment costs.
- Other means of improving FRT capability such as fast valving for steam turbines → increased equipment costs and more complex control systems.

#### **Recommendation:**

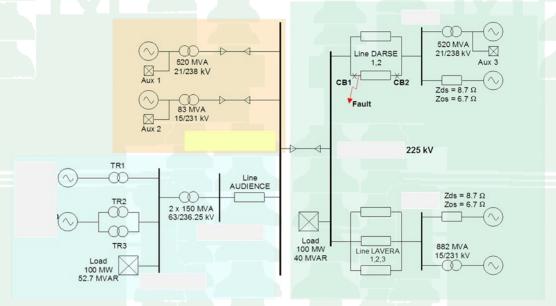
- Given diminishing performance benefit → CF should not exceed 2.0.
- Employ other means for FRT as dictated by system simulations



# **Auto Re-Closing**

#### IEEE C50.13 states that:

- Rapid reclosure (successful & unsuccessful) :
  - results in shaft torques which are statistical in nature
  - could lead to cumulative fatigue damage to shafts
- Generalized torsional stress requirements are not possible
- Unit-specific study is recommended to be performed



Typical system representation for modeling re-closing events

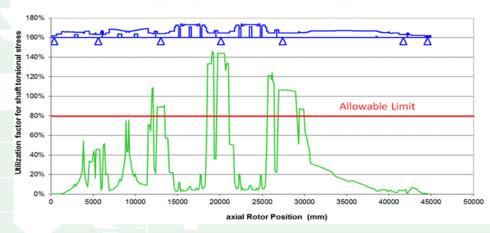


# **Auto Re-Closing**

- Grid codes generally require units to withstand 1or 3-phase auto-reclosures without tripping
- Protective measures:
  - Supervision by synchro-check relay to avoid reclosing onto a fault
  - Specific study needed, considering statistical nature of events vs. "worst" case
- → Machine shaft integrity shall be considered 1st priority for grid reliability / availability







Representative torque and shaft stresses due to re-closing



## Power Output Vs. Frequency

Sample Output vs Frequency Requirements

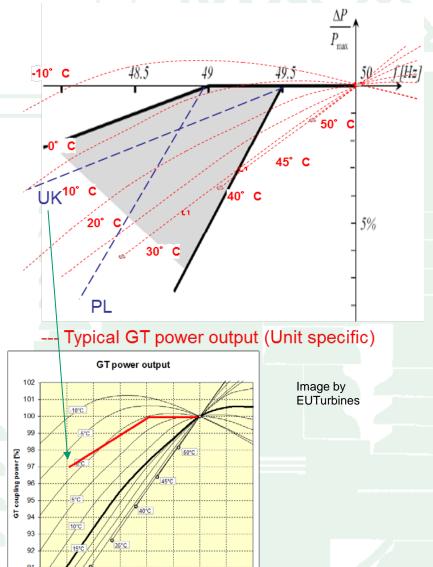
#### EU grid code

**BLUE** lines

- Below 49.5 Hz reduction rate of 10% per 1 Hz Frequency drop
- Below 49 Hz: reduction rate of 2% per 1 Hz Frequency drop
- UK and Poland grid code
   requirements shown by dotted

# Physical behavior of CGT

- Significantly decreased output with higher ambient temperature
- Therefore limitation of requirement to 25°C in UK



GT speed [%]



# MW vs F Design Impact

- Need to "derate" units to provide headroom for an event that may never occur.
- Higher €/kW Capex for dead capacity, losing best efficiency. Creates a 0.5 B€cost\*
- Need to develop and install compensation mechanisms with inherent activation delay times. Creates additional 0.1 B€cost\*.
- <u>Recommendation:</u> Do not specify capability, but require submission of capability by manufacturers. Adjust load shedding schemes through simulations.

\*Estimates by EUTurbines for subject market (Brussels presentation 2013)



## **Summary**

- Evolution in the power system is driving changes in the grid requirements for power generation equipment.
- Equipment designed to current machine standards does not necessary meet the grid code requirements.
- Grid operators must also consider the physical limitations and the cost impact when defining grid requirements for power generation equipment.
- There is an urgent need to identify existing gaps and harmonize design standards with grid code requirements.
- Industry consultations are important to ensure design standards and grid code requirements are harmonized.