

Trajectory Sensitivity Analysis as a Means of Performing Dynamic Load Sensitivity Studies in Power System Planning

Parag Mitra Vijay Vittal
Arizona State University
USA

Pouyan Pourbeik Anish Gaikwad
Electric Power Research Institute
USA

❖ Load modeling for power system planning

- ❖ Load modelling is one of the most important aspects of time-domain simulations for power system planning.
- ❖ North American Reliability Corporation (NERC) requires system peak load levels to be represented by load models considering behavior of induction motors¹
- ❖ Significant work done by the WECC load modelling task force led to the development of the composite load model (*cmpldw*).
- ❖ As the NERC standards become enforced in the near future, utilities in North America will need to adopt dynamic load model structures similar to the WECC composite load model (*cmpldw*).

1. NERC TPL Standard -001-4 “System peak load levels shall include a load model which represents the expected dynamic behavior of loads that could impact the study area, considering the behavior of induction motor loads.”

❖ Challenges in load modeling

- ❖ The WECC composite load model represents an aggregation of different types of load at the substation node.
- ❖ The exact composition of different types of loads in the composite load model is not known during the planning stage.
- ❖ This introduces significant uncertainties into the model.
- ❖ To deal with uncertainties, it becomes important to develop a systematic approach for performing load sensitivity studies.
- ❖ This paper presents some initial research results for using a methodology known as trajectory sensitivity analysis for performing load sensitivity studies.

❖ Trajectory sensitivity analysis

- ❖ A power system can be represented by a set of differential algebraic equations

$$\dot{x} = f(x, y, \lambda) \quad (1)$$

$$g^-(x, y, \lambda) = 0 \text{ for } y_k < 0 \quad (2)$$

$$g^+(x, y, \lambda) = 0 \text{ for } y_k \geq 0 \quad (3)$$

- ❖ x represents network dynamic states (rotor angles, frequency, flux)
- ❖ y represents network algebraic variables (network voltages and angles)
- ❖ λ represents the systems parameters of interest (for our case λ represents the load parameters)
- ❖ Equations (2) and (3) represent the pre and post network algebraic equations following a discrete event. For example, it could represent the power consumed by a 1 ϕ - induction motor (modeled by algebraic eqs e.g *ld1pac*) before and after it stalls. The stalling conditions are modeled in the form $y_k=0$

❖ Trajectory sensitivity analysis

- ❖ Sensitivity of state variables to parameter λ is given by $\frac{\partial x(t)}{\partial \lambda}$
- ❖ Sensitivity of algebraic variables to parameter λ is given by $\frac{\partial y(t)}{\partial \lambda}$
- ❖ The predicted trajectories can be calculated by a first order approximation as

$$x(t)_{pred} = x(t)_{old} + \frac{\partial x}{\partial \lambda} \Delta \lambda \quad (4)$$

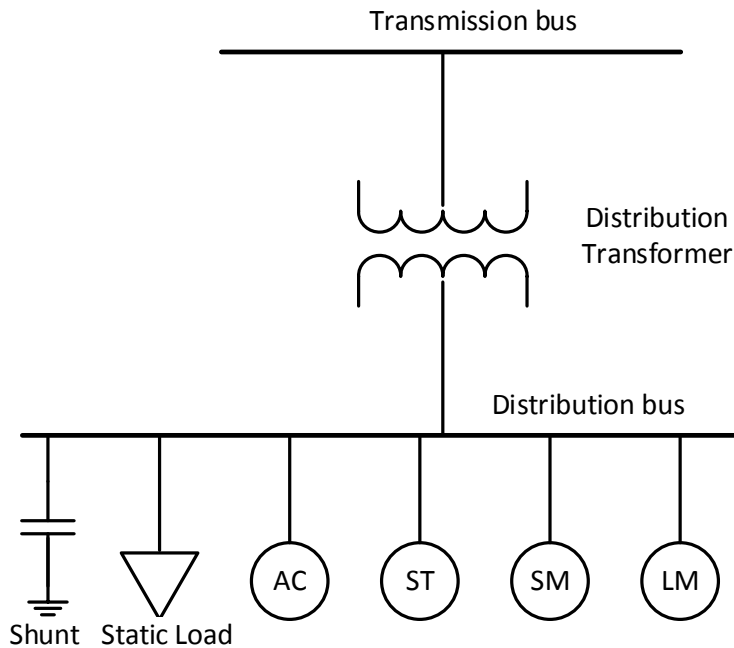
$$y(t)_{pred} = y(t)_{old} + \frac{\partial y}{\partial \lambda} \Delta \lambda \quad (5)$$

❖ Trajectory sensitivity analysis

- ❖ Calculation of the sensitivities requires the power flow Jacobian at each step of the time domain solution.
- ❖ The power flow Jacobian is available as a by-product of a traditional time domain simulation routine, which incorporates an implicit integration algorithm (trapezoidal rule is an example of an implicit integration algorithm)
- ❖ Runtime availability of the power flow Jacobian reduces the computation effort in evaluating the sensitivities and it can be done simultaneously while performing a time domain simulation
- ❖ The sensitivities of different parameters are independent of each other. These can be evaluated in parallel using an appropriate parallel computing architecture, enabling additional savings in time

❖ System and load model

- ❖ The WECC 2012 peak summer case was used in the study. The study was performed using a Matlab based open source software package PSAT
- ❖ A WECC composite load model was used in order to ensure that the test case closely represented a practical real-life scenario.



Composite load model

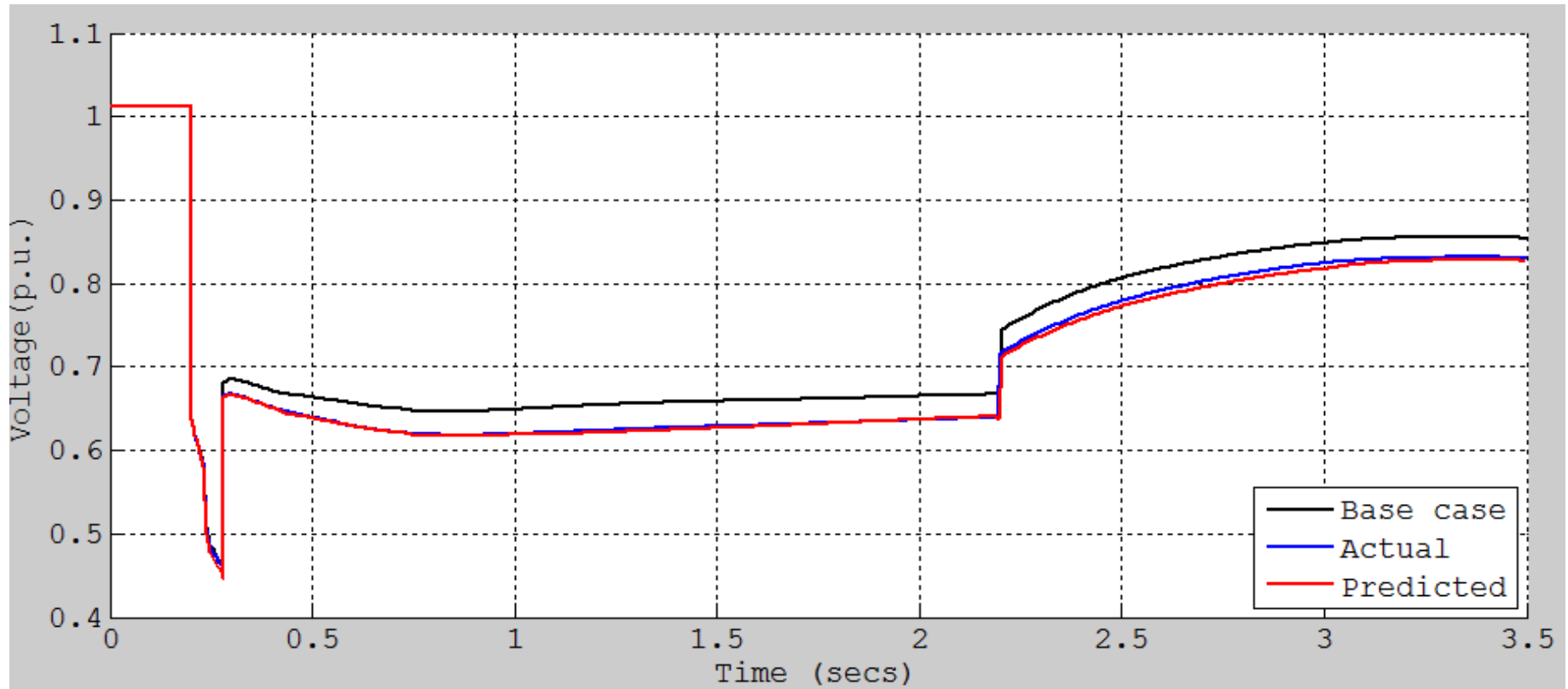
| WECC 2012 Case | |
|---|--------|
| Buses | 17047 |
| Generators | 2 059 |
| Transformers | 5 727 |
| Branches | 13 178 |
| Loads | 6 781 |
| Loads represented by composite load model | 3729 |

| | |
|----|------------------|
| LM | Large motors |
| SM | Small motors |
| ST | Trip motors |
| AC | Air conditioners |

❖ Application to the WECC system

- ❖ Trajectory sensitivity analysis was used to study the effect of change in load composition at different buses on the system algebraic and state variables following a single disturbance.
- ❖ A WECC 2012 summer peak system model was used for this work. A three-phase fault was applied on a major 500 kV line. The fault is cleared by opening the line after 5 cycles.
- ❖ The sensitivity of voltage and frequency to percentage changes in the air-conditioning (AC) load at 20 buses were studied.
- ❖ ACs were observed to stall at these 20 buses and hence these 20 buses were selected to study the effect of change in load composition.
- ❖ ΔK_p refers to the percentage change in AC load at each bus

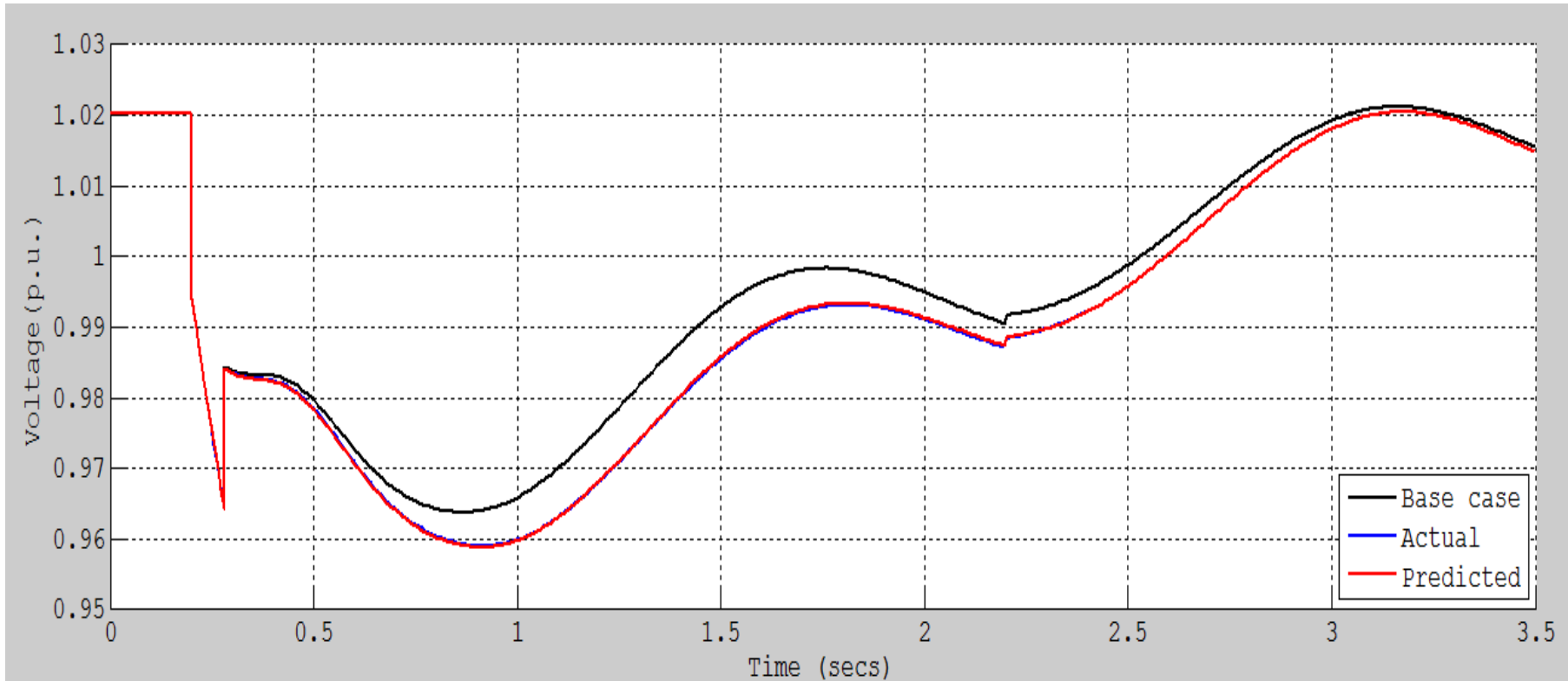
❖ Application to the WECC system



Actual and predicted voltage at bus 611 for a ΔK_p of 5 at 20 buses

❖ This load bus is electrically close to the fault location

❖ Application to the WECC system



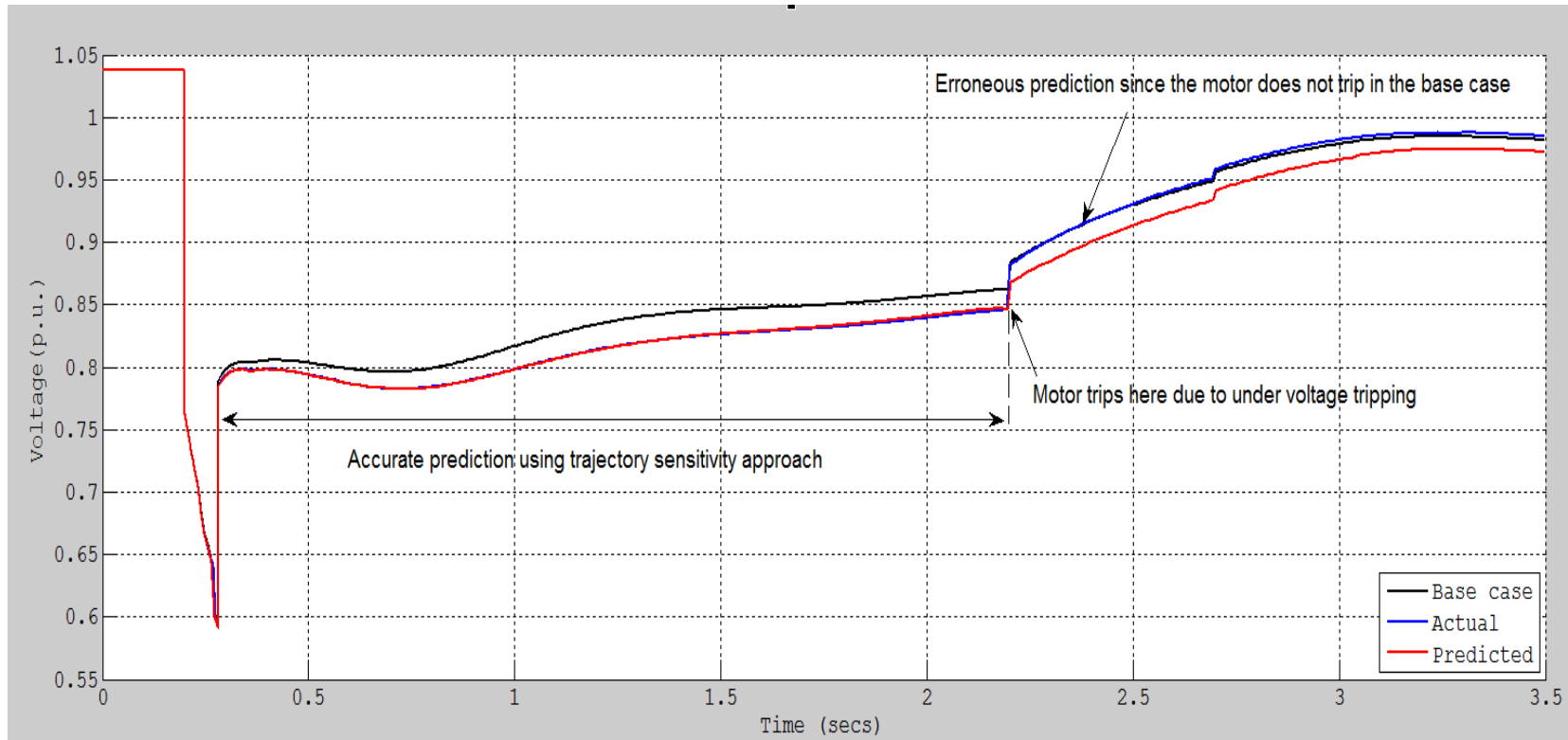
Actual and predicted voltage at bus 212 for a ΔK_p of 5 at 20 buses

❖ This load bus is electrically far from the fault location

❖ Effect of relay, contactors and discontinuous load characteristics

- ❖ Relays and/or contactors and discontinuities in the load characteristics introduce severe non linearity in the load models.
- ❖ Non linear models lead to approximation errors in a trajectory sensitivity based approach.
- ❖ Trajectory sensitivity based approach can be erroneous when the base case and the actual case to be predicted do not encounter and traverse same switching surfaces.
- ❖ For example, the base case and actual scenario (to be predicted) should have same number of motors tripping (motorw model) and same number of air-conditioners (stalling / restarting) to get an accurate linear prediction of trajectories.
- ❖ For the present scenario simulated, air-conditioners account for majority of the load. Stalling of additional AC units has a pronounced effect on the linear approximation.

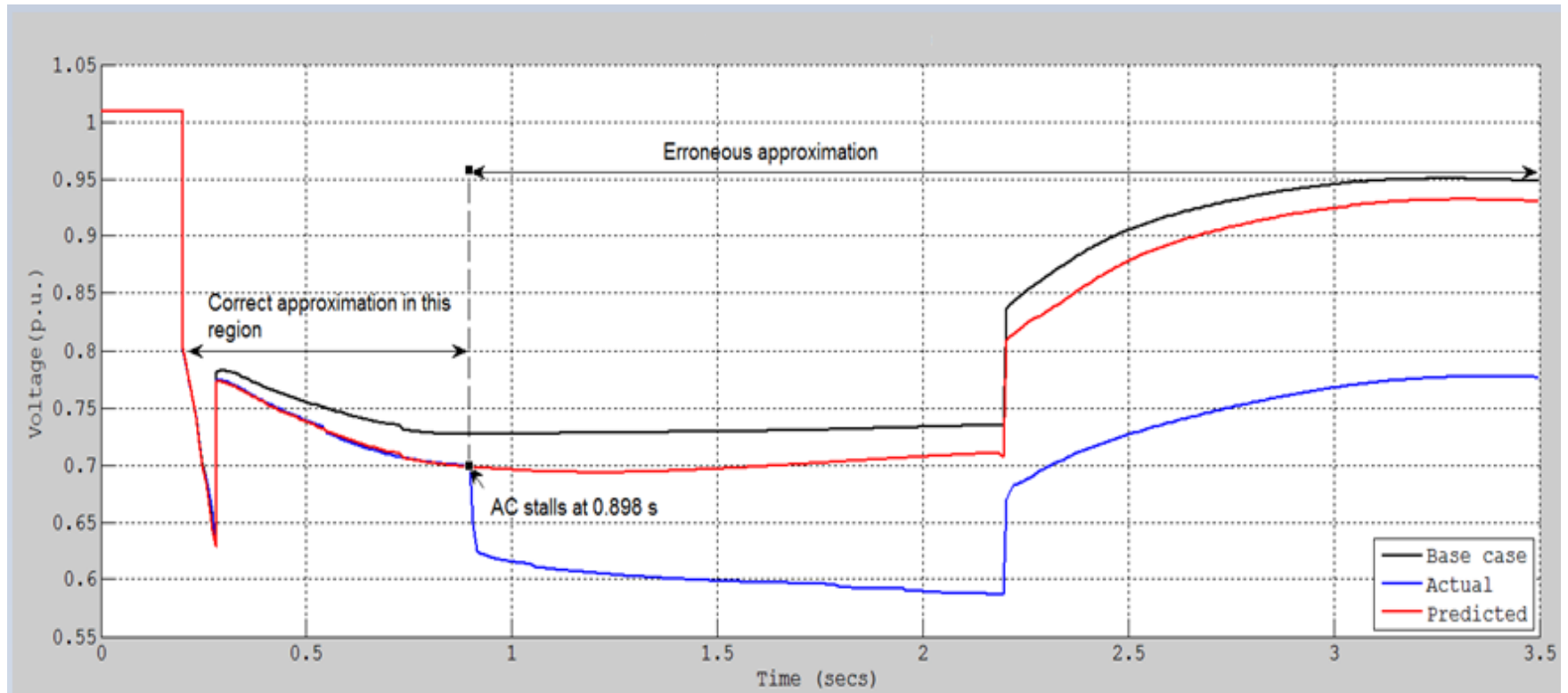
❖ Effect of different number of small motor (motorw) tripping in actual and base case



Actual and predicted voltage at bus 419 for 5 percent load change at 20 buses

- ❖ 14% of the total load is represented by small motor which is relatively small.
- ❖ Effect on error in trajectory approximation is localized

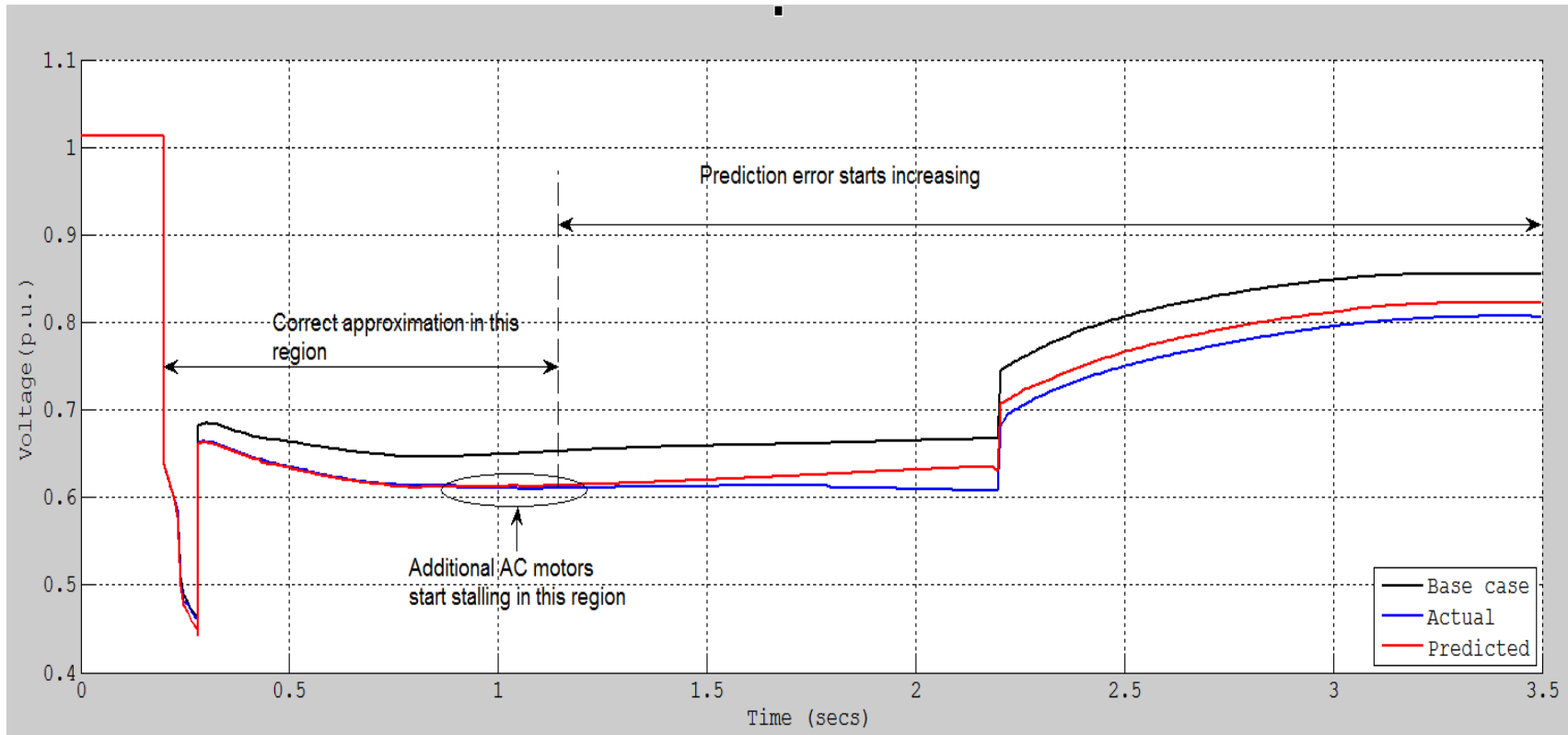
❖ Effect of different number of air conditioners stalling in actual and base case



Actual and predicted voltage at bus 420 for 6 percent load change at 20 buses

- ❖ 30% of the total load is represented by air-conditioners.
- ❖ The effect is more pronounced at this bus than at buses further away.

❖ Effect of different number of air conditioners stalling in actual and base case



Actual and predicted voltage at bus 611 for 6 percent load change at 20 buses

- ❖ The effect of different number of air-conditioners stalling can be seen but the error is less pronounced.

❖ Solution metrics for trajectory sensitivity analysis

| Routines | Time (N-R without optimal multiplier) |
|--|--|
| Time domain simulation (includes storing Jacobian) | 3487.729 sec |
| Calculate initial values of sensitivities | 1.708 sec |
| Calculate the sensitivities | 913.87 sec |
| Create the final trajectory | 32.29 sec |
| Total time | 4435.59 sec (74 mins) |
| Size of file containing Jacobian entries | 9 GB |

- ❖ It should be noted that a trapezoidal method of integration is used in the trajectory sensitivity analysis. The increased simulation time is due to increased Newton-Raphson iterations required for convergence of solution during disturbances

❖ Solution metrics for trajectory sensitivity analysis

- ❖ To reduce the simulation time an optimal multiplier is introduced
- ❖ The intermediate step of a time domain simulation can be stated as a set of nonlinear equations given by

$$f(x) = 0 \quad (6)$$

- ❖ If the initial guess of the solution vector is x_0 then the updated solution vector can be calculated as

$$-f(x_0) = J\Delta x \quad (7)$$

$$x_1 = x_0 + \Delta x \quad (8)$$

J : Jacobian matrix containing the partial derivatives of f w.r.t x

Δx : Correction vector by which x_0 is incremented

❖ Solution metrics for trajectory sensitivity analysis

- ❖ NR method can be modified by introducing an optimal multiplier α , such the new estimate for the solution is given by

$$x_1 = x_0 + \alpha\Delta x \quad (9)$$

- ❖ The value of α is calculated by solving a one dimensional minimization problem

$$\alpha = \arg \min(f(x_0 + \alpha\Delta x)^t f(x_0 + \alpha\Delta x)) \quad (10)$$

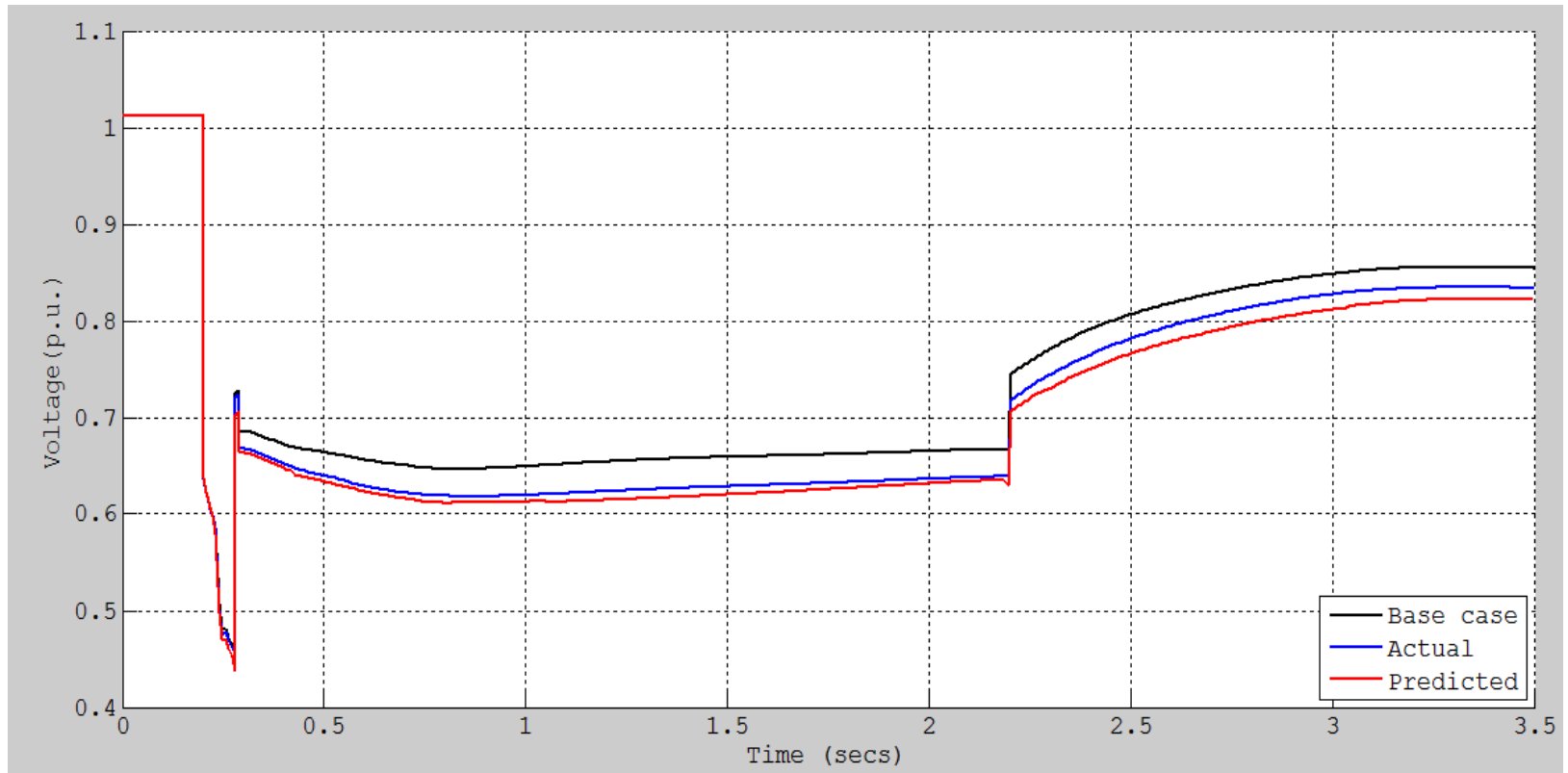
- ❖ The exact solution of the one dimensional optimization problem in (10) is time consuming and a local minimizer can be obtained by methods like line search algorithms or interpolation methods.
- ❖ A cubic interpolation method has been used for this study.

❖ Solution metrics for trajectory sensitivity analysis

| Routines | Time (N-R without optimal multiplier) | Time (N-R with optimal multiplier) |
|--|--|---|
| Time domain simulation (includes storing Jacobian) | 3487.729 sec | 1695.548 sec |
| Calculate initial values of sensitivities | 1.708 sec | No change |
| Calculate the sensitivities | 913.87 sec | 353.97 sec |
| Create the final trajectory | 32.29 sec | No change |
| Total time | 4435.59 sec (74 mins) | 2083.108 sec (35 mins) |
| Size of file containing Jacobian entries | 9 GB | 5 GB |

- ❖ A comparison of the two approaches shows that using an optimal multiplier results in a substantial reduction in computation time

❖ Effect of different number of air conditioners stalling in actual and base case



Actual and predicted voltage at bus 15611 for 5 percent load change at 20 buses (N-R method with optimal multiplier)

- ❖ Using an optimal multiplier does not introduce any significant error in trajectory approximation.

❖ Conclusions

- ❖ One of the key challenges in load modeling is determining the composition of aggregated model parameters.
- ❖ An approach to address this issue is the application of load model sensitivity analysis using trajectory sensitivity.
- ❖ The main benefit of this method is that it allows a planner to study multiple scenarios with uncertain load parameters without the need of multiple simulations.
- ❖ Multiple sensitivities can be computed in parallel enabling additional savings in time.
- ❖ The main disadvantage at present is that being a linear approach it cannot sufficiently handle severe non-linearity in load models.
- ❖ The computation time is relatively higher due to the use of an implicit integration algorithm. However it can be reduced substantially by introducing optimal multipliers.